# Lunar Landing Research Vehicle

# WEIGHT and BALANCE HANDBOOK

REPORT NO. 7161-954002

1 APRIL 1964

## MANUFACTURED

BY



FOR NATIONAL AERONAUTIC AND SPACE ADMINISTRATION
CONTRACT NAS 4-234

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# **FOREWORD**

The majority of the weights, arms, and moments in this Handbook are based on calculations. Actual weighed and measured values should be substituted when they become available.

All weights and arms are taken from detail weight records but are all rounded off to the nearest tenth of a unit. Therefore, the product of weight and arm may deviate slightly from the moment value shown.

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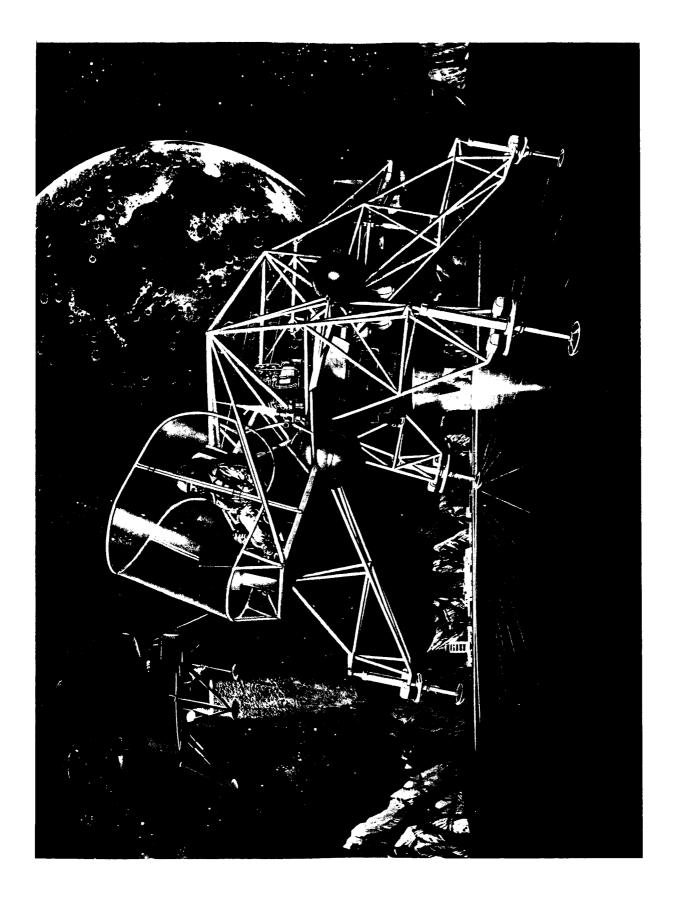
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## SECTION I

### TECHNICAL DATA

# 1.1. DEFINITIONS.

- 1.1.1. <u>Basic Weight.</u> Basic weight is defined as the weight of the Lunar Landing Research Vehicle (LLRV) and its normal operational equipment. (See Figure 1-1.) It includes the weight of the hydraulic and engine oil systems filled to capacity, and the helium pressurization gas under normal operating pressure. It also includes the weights of JP4 fuel and hydrogen peroxide contained in the distribution and supply lines from the tank outlets to the engine fuel pump and solenoid valves respectively.
- 1.1.2. Operating Weight Empty. Operating weight empty is defined as the basic weight plus the weight of the fully equipped pilot.
- 1.1.3. Gross Takeoff Weight. Gross takeoff weight is defined as the weight at the moment of lift-off. It is obtained by adding the weights of JP4 and hydrogen peroxide fuels contained within the fuel tanks to the operating weight empty. It does not include the weight of fuels used in runup and checkout and is subject to limitations governed by takeoff altitude and ambient temperature.

## 1.2. GROSS TAKEOFF WEIGHT LIMITATIONS.

The allowable gross takeoff weight is contractually limited to 95.5 percent of the installed jet engine thrust at takeoff rating. (Refer to the LLRV Flight Manual, Bell Aerosystems Company Report 7161-954005, for information regarding determination of the maximum allowable gross takeoff weight.) The maximum allowable gross takeoff weight is not limited by structural considerations.

# 1.3. CENTER OF GRAVITY LIMITS.

# 1.3.1. Vertical Center of Gravity Limits. -

# 1.3.1.1. Vehicle Without Gimballed Items. -

- 0.0 to 0.5 inch below WL 200 (gimbal C) at gross takeoff weight.
- 0.0 to 0.5 inch below WL 200 (gimbal Q) at operating weight empty.

# 1.3.1.2. Gimballed Items (Gimbal Ring and All Items Supported Thereby). -

0.0 to 1.5 inches below WL 200 (gimbal \$\mathbb{G}\$).

# 1.3.2. Lateral and Horizontal Center of Gravity Limits. -

 $\pm 0.25$  inch from intersection of pitch and roll reference axes (center of gimbals) for all combinations of vehicle and engine at all weights.

# 1.4. LEVELLING PROVISIONS.

Two sets of levelling lugs are provided on the vehicle. They are located on the main structural ring and provide means for determining pitch and roll angles. The locations of the levelling lugs are identified in Figure 1-2.

## 1.5. WEIGHING DATUMS.

No jig points are provided on the vehicle. The datum for all measurements of lateral and horizontal centers of gravity is the engine centerline. The datum for measurement of the vertical center of gravity is the horizontal plane through the gimbal axes.

# 1.6. REFERENCE AXES.

The reference axes are a standard set of orthogonal roll, pitch, and yaw axes, designated the x, y, and z axes, respectively. (See Figure 1-2.)

## 1.7. REFERENCE DATUMS.

Reference datums are located 200 inches from the intersection of the reference axes. (See Figure 1-2.)

# 1.8. HELIUM GAS DATA.

The weights and moments for helium gas are shown in Table 1-1. The values shown are calculated; actual measured values should be substituted when they become available.

# 1.9. ENGINE OIL DATA.

The weight and moment for engine oil is shown in Table 1-2. The values shown are calculated; actual measured values should be substituted when they become available.

# 1.10 CREW DATA.

Weights and moments for various weights of pilots are shown in Table 1-3. The values shown are calculated; actual measured values should be substituted when they become available.

TABLE 1-1
HELIUM GAS DATA

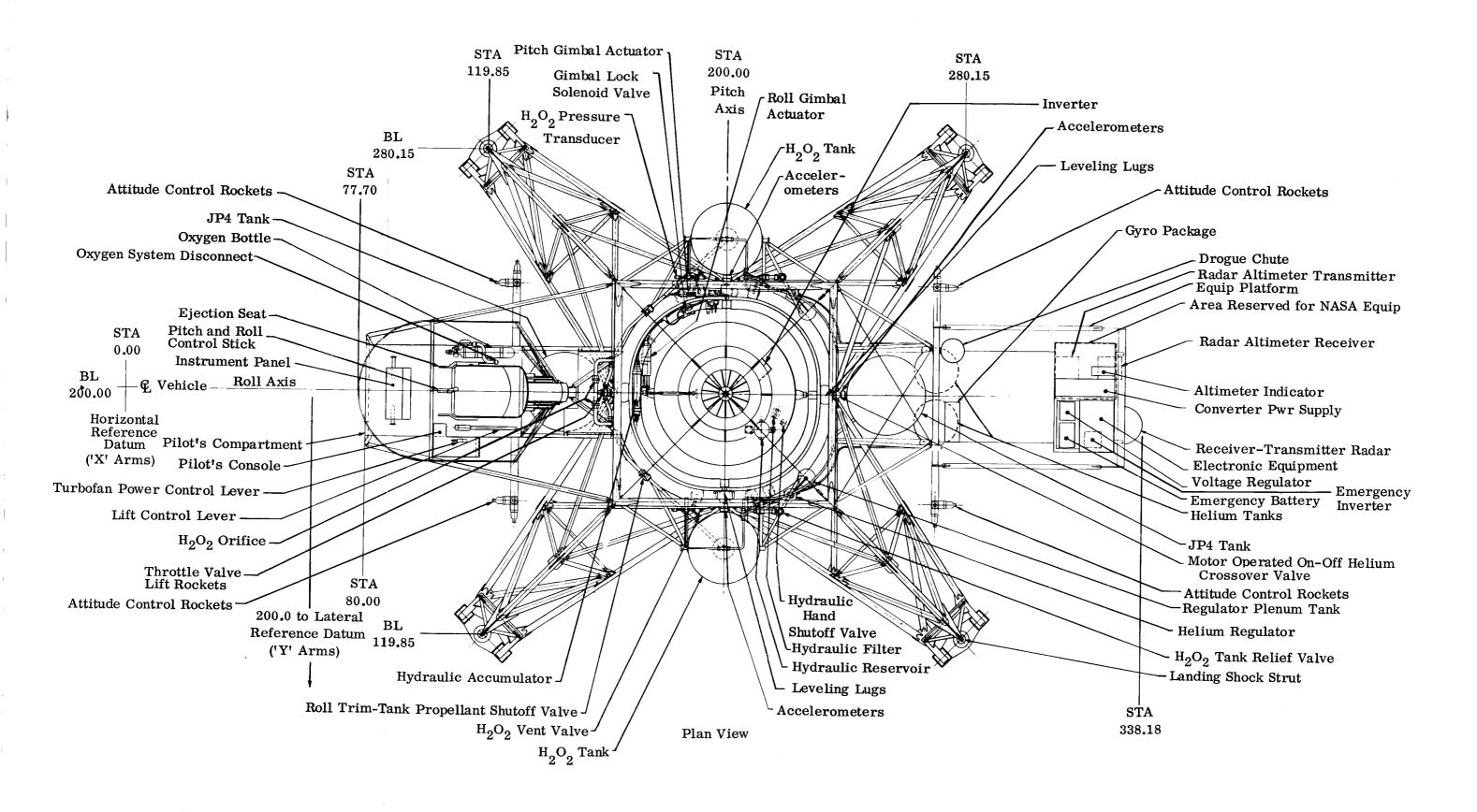
TANK PRESSURE PSIA	WEIGHT OF HELIUM (TWO TANKS) POUNDS W	ARM INCHES x	MOMENT POUND- INCHES Wx	ARM INCHES y	MOMENT POUND- INCHES Wy	ARM INCHES z	MOMENT POUND- INCHES Wz
3500	4.64	270.0	1253	200.0	928	191.5	888
3250	4.34	270.0	1172	200.0	868	191.5	831
3000	4.04	270.0	1091	200.0	808	191.5	774
2750	3.73	270.0	1007	200.0	746	191.5	714
2500	3.42	270.0	923	200.0	684	191.5	655

TABLE 1-2
ENGINE OIL DATA

			OIL RESER ALLON CAF		·		
U.S. GALLONS	WEIGHT POUNDS*	ARM** INCHES x	MOMENT POUND- INCHES Wx	ARM** INCHES y	MOMENT POUND- INCHES Wy	ARM** INCHES	MOMENT POUND- INCHES Wz
1.0	7.50	194.0	1455	189.0	1418	188.4	1413

<sup>\*</sup> Based on lubricating oil Specification MIL-L-7808E, 7.50 pounds per U.S. gallon at 60 degrees F.

<sup>\*\*</sup> Engine vertical.



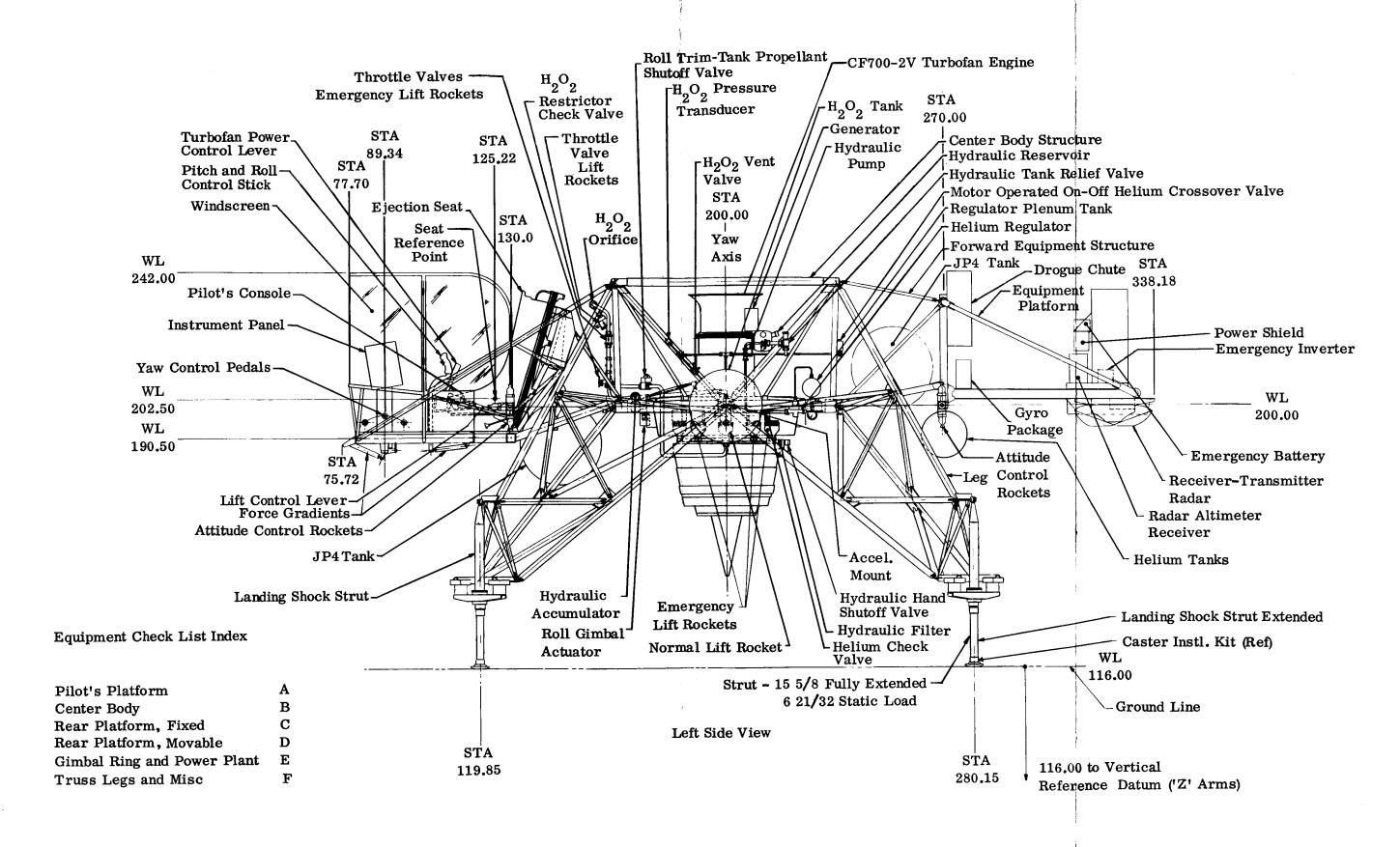


Figure 1-2. LLRV General Arrangement

TABLE 1-3 CREW DATA

PILOT* WEIGHT POUNDS W	ARM** INCHES x	MOMENT POUND- INCHES Wx	ARM INCHES y	MOMENT POUND- INCHES Wy	ARM** INCHES z	MOMENT POUND- INCHES Wz
230	120.2	27,646	200.0	<b>46,0</b> 00 .	215.4	49,542
220	120.2	26,444	200.0	44,000	215.4	47,388
210	120.2	25,242	200.0	42,000	215.4	45,234
200	120.2	24,040	200.0	40,000	215.4	43,080
190	120.2	22,838	200.0	38,000	215.4	40,926
180	120.2	21.636	200.0	36,000	215.4	38,772
170	120.2	20,434	200.0	34,000	215.4	36,618
160	120.2	19,232	200.0	32,000	215.4	34,464
150	120.2	18,030	200.0	30,000	215.4	32,310

<sup>\*</sup>Pilot weight includes all clothing and equipment worn or carried to the vehicle, but does not include the weight of the parachute.

## 1.11. JP4 FUEL DATA.

The weights and moments for varying quantities of JP4 fuel contained in the fuel tanks are shown in Table 1-4. The weight and moments for all JP4 fuel elsewhere in the fuel system (i.e., between tank outlets and engine fuel pump) are shown in Table 1-5. This fuel is part of the vehicle basic weight. (See Paragraph 1.1.1.). The maximum volume of fuel in each tank with filler cap open is calculated as 34.4 U.S. gallons. Ensure that the fuel weight difference between the two tanks does not exceed one pound at takeoff. All values shown in the fuel tables are calculated; actual measured values should be substituted when they become available.

<sup>\*\*</sup>All centers of gravity are based upon the seat reference point at the centerline of the seat in the neutral position (Reference MS 33575).

TABLE 1-4
JP4 FUEL IN TANKS

							<del>,</del>
TOTAL LOADED* WEIGHT POUNDS (TWO TANKS) W		ARM** INCHES x	MOMENT POUND- INCHES Wx	ARM** INCHES	MOMENT POUND- INCHES Wy	ARM** INCHES z	MOMENT POUND- INCHES Wz
447 425 400 375 350 325 300 275 250 225	68.8 65.4 61.5 57.7 53.8 50.0 46.2 42.3 38.5 34.6	200.0 200.0 200.0 200.0 200.0 200.0 200.0 200.0 200.0	89,400 85,000 80,000 75,000 70,000 65,000 55,000 50,000 45,000	200.0 200.0 200.0 200.0 200.0 200.0 200.0 200.0 200.0	89,400 85,000 80,000 75,000 70,000 65,000 55,000 50,000 45,000	199.1 198.7 198.2 197.7 197.2 196.8 196.3 195.8 195.3	89,018 84,433 79,294 74,154 69,036 63,958 58,892 53,857 48,836 43,840
200 175 150 125 100 75 50 25	30.8 26.9 23.1 19.2 15.4 11.5 7.7 3.8	200.0 200.0 200.0 200.0 200.0 200.0 200.0 200.0	40,000 35,000 30,000 25,000 20,000 15,000 5,000	200.0 200.0 200.0 200.0 200.0 200.0 200.0 200.0	40,000 35,000 30,000 25,000 20,000 15,000 5,000	194.3 193.8 193.1 192.6 192.0 191.3 190.5 189.5	38,869 33,923 28,972 24,074 19,204 14,351 9,527 4,739

<sup>\*</sup>Table based on JP4 fuel at 6.5 pounds per U.S. Gallon at 60 degrees F.

TABLE 1-5
JP4 FUEL IN LINES

TOTAL WEIGHT W POUNDS	VOLUME U.S. GALLONS	ARM x INCHES	MOMENT Wx POUND- INCHES	ARM y INCHES	MOMENT Wy POUND- INCHES	ARM z INCHES	MOMENT Wz POUND- INCHES
			,				·

Vehicle in level attitude

<sup>\*\*</sup>Vehicle in level attitude.

# 1.12. HYDROGEN PEROXIDE DATA.

The weights and moments for varying quantities of hydrogen peroxide contained in the tanks are shown in Table 1-6. The weight and moments for all hydrogen peroxide elsewhere in the system (i.e., between the tank outlets and thruster solenoid valves) are shown in Table 1-7. This amount of hydrogen peroxide is part of the vehicle basic weight. (See Paragraph 1.1.1.). The maximum volume of hydrogen peroxide in each tank is calculated as 28.85 U.S. gallons with no ullage space. Ensure that the hydrogen peroxide weight difference between the two tanks does not exceed one pound at takeoff. All values shown in the hydrogen peroxide tables are calculated; actual measured values should be substituted when they become available.

### 1.13. BALLAST.

This vehicle is not intended to carry ballast and no special means for attachment of ballast is provided.

# 1.14. EQUIPMENT CHECKLIST.

The weight, arms, and moments for removable items of equipment are listed in the LLRV equipment checklist, Table 1-8. When items are permanently removed from the vehicle, they should be deleted from the checklist. New items which are permanent installations should be added to the checklist. When check marks are entered in the "ON VEHICLE" column, they serve as the inventory of equipment included in the basic weight. Inventories should be made periodically, but are required specifically when:

- (a) The vehicle undergoes modification, major overhaul, or repair.
- (b) Changes in equipment are made for a different type of operation or mission.
- (c) The vehicle is reweighed.

Make certain that the same date is entered over the "CHECK" heading in the LLRV equipment checklist and in the date column on the basic weight and balance record (Paragraph 2.5.7) for the corresponding corrected basic weight and centers of gravity.

TABLE 1-6 HYDROGEN PEROXIDE IN TANKS

	TOT IDEE						1
'	VOLUME						İ
TOTAL LOADED*	U.S. GAL-		MOMENT		MOMENT		MOMENT
WEIGHT POUNDS	LONS (TWO	ARM**	POUND-	ARM**	POUND-	ARM**	POUND-
(TWO TANKS)	TANKS)	INCHES	INCHES	INCHES	INCHES	INCHES	INCHES
w	·	x	Wx	у	Wy	z	Wz
670	<b>57.</b> 8	200.0	134,000	200.0	134,000	200.0	134,000
650	56.0	200.0	130,000	200.0	130,000	199.8	129,854
625	53.9	200.0	125,000	200.0	125,000	199.4	124,616
600	51.7	200.0	120,000	200.0	120,000	199.0	119,415
575	49.6	200.0	115,000	200.0	115,000	198.6	114,209
550	47.4	200.0	110,000	200.0	110,000	198.3	109,090
525	45.2	200.0	105,000	200.0	105,000	198.0	103,963
500	43.1	200.0	100,000	200.0	100,000	197.7	98,863
475	40.9	200.0	95,000	200.0	95,000	197.4	93,767
450	38.8	200.0	90,000	200.0	90,000	197.1	88,706
425	36.6	200.0	85,000	200.0	85,000	196.8	83,651
400	34.5	200.0	80,000	200.0	80,000	196.5	78,594
375	32.3	200.0	75,000	200.0	75,000	196.2	73,562
350	30.2	200.0	70,000	200.0	70,000	195.8	68,542
325	28.0	200.0	65,000	200.0	65,000	195.5	63,546
300	25.9	200.0	60,000	200.0	60,000	195.2	58,553 (
275	23.7	200.0	55,000	200.0	55,000	194.8	53,580
250	21.6	200.0	50,000	200.0	50,000	194.5	48,631
225	19.4	200.0	45,000	200.0	45,000	194.1	43,678
200	17.2	200.0	40,000	200.0	40,000	193.8	38,755
175	15.1	200.0	35,000	200.0	35,000	193.4	33,849
150	12.9	200.0	30,000	200.0	30,000	193.0	28,948
125	10.8	200.0	25,000	200.0	25,000	192.5	24,066
100	8.6	200.0	20,000	200.0	20,000	192.0	19,202
75	6.5	200.0	15,000	200.0	15,000	191.5	14,364
50	4.3	200.0	10,000	200.0	10,000	191.0	9,551
25	2.2	200.0	5,000	200.0	5,000	190.2	4,756
	l	l	l	i	1	l .	

<sup>\*</sup>Table based on 90 percent  $\rm H_2O_2$  at 11.60 pounds per U.S. gallon at 70 degrees F. \*\*Vehicle in level attitude

TABLE 1-7
HYDROGEN PEROXIDE IN LINES

TOTAL WEIGHT W POUNDS	VOLUME U.S. GALLONS	ARM* x INCHES	MOMENT Wx POUND- INCHES	ARM* y INCHES	MOMENT Wy POUND- INCHES	ARM* z INCHES	MOMENT Wz POUND- INCHES

<sup>\*</sup>Vehicle in level attitude.

TABLE 1-8 LLRV EQUIPMENT CHECKLIST

	•				,			
	DATE							
	Ì			СНЕ	CK NUM	IBERS		
		1	2	3	4	5 .	6	7
		Δλ	ξX	XX.	3.7	3Y	3.7	37
		AT'S	NTF	LLN	NTI	ITN	TA	ILN
		JLE 5 E	S E	OLE 5 E	CLE	CLE	CLE -5 E	CLE
5	MOMENT POUND- INCHES Wz	ON VEHICLE FORM II-5 ENTRY						
	2160 1067 1067 20,800 8119 364 723 364 364 1813 176 176 165 258 258 258 254 128							
	1850 375 1817 375 187							
			On Veh	icle Vehicle				

LOCATION AND ITEM NUMBER	DESCRIPTION AND PART NUMBER	WEIGHT POUNDS W	ARM INCHES x	MOMENT POUND- INCHES Wx	ARM INCHES y	MOMENT POUND- INCHES Wy	ARM INCHES z	MOMENT POUND- INCHES Wz	ON VEHI FORM II	ON VEHI FORM II	ON VEHI FORM II	ON VEHI FORM II	ON VEH	ON VEH	ON VEH	-
A	PILOTS PLATFORM				.											
A-1	Cockpit Enclosure, Windshield, 7161-150003-47	9.7	91.0	883	200.0	1940	222.7	2160								
A-2	Cockpit Enclosure Door, LH 7161-150003-29	4.7	115.7	544	176.8	831	227.0	1067								
A-3	Cockpit Enclosure Door RH 7161-150003-30	4.7	115.7	5 <del>44</del>	223.2	1049	227.0	1067							1 1	
A-4 A	Ejection Seat, Weber, 802900	99.2	125.4	12,438	200.0	19,838	209.7	20,800		1 1	1					
A-5	Parachute	20.0														
A-6	Rocket Catapult	18.3					1									
A-7 🗘	Instrument Panel, 7161-561001	38.0	90.8	3451	197.7	7515	213.6	8119	•						h	
A-8	Indicator, Normal Acceleration	1.7	91.0	155	196.4	334	214.0	364	•				1			. :
A-9	Indicator, Drift and Heading	3.3	91.0	300	200.0	660	219.2	723				1 1				
A-10	Indicator, Vertical Velocity	1.7	91.0	155	203.9	347	214.0	364								
A-11	Sensitive Altimeter	1.7	91.0	155	205.1	349	214.0	364			1				1.	
A-12	Attitude Indicator, 4060-C	8.5	91.0	774	200.0	1700	213.3	1813								
A-13	Clock, AN5743-2	0.8	91.0	73	196.2	157	220.6	176		1 1			1 1			
A-14	Tachometer, Indicator, 8DJ81-AAA	0.8	91.0	73	189.4	152	220.5	176		! <b> </b>						
A-15	E.G.T. Indicator, 1121	0.8	91.0	68	191.7	144	220.5	165		<u> </u>						
A-16	Indicator, Pressure, H2O2 Tank	1.2	91.0	109	189.4	227	214.9	258							1	
A-17	Indicator, Pressure Lift Rocket Chamber	1.2	91.0	109	191.7	230	214.9	258		1					-	
A-18	Indicator, Pressure, Helium Source	1.2	91.0	109	190.7	229	212.0	254	1.	-						
A-19	Coarse Altimeter, 450610	0.6	91.0	53	204.4	118	220.1	128					1 1			
A-20	Course IIIIII	·											1			
A-21	•				İ								1	1	1 1	
A-22				i	1								1			
A-23 🗥	Console 7161-561002	9.3	109.7	1020	180.8	1681	198.9	1850				1				
A-24	Transmitter - Receiver, FM		104.1		181.6		201.5	Ì								
A-25	Throttle Quadrant 7161-435010-1	1.8	108.2	195	183.4	330	208.2	375	1 1							
A-26	Infottie quadrant (101 100010 1			<i>'</i> .					1							
A-27	Oxygen bottle, 5600-1C1-C4A	9.3	119.0	1110	213.0	1987	194.8	1817					1			
A-28	Force Gradient, 204-001-045-5 (2)	2.0	111.2	222	200.0	400	187.5	375								
A-29	Force Gradient, 204-001-045-7 (1)	1.0	83.5	84	196.3	196	187.4	187					1 1			
A-30 🖄						İ			ļ				1			-
12.00/22	Camera						1.		1	On Vel						
$\Lambda$	Including Subsequent Indented Items										Vehicle					
<b>A</b>	NASA Payload Item								X =	Not Ap	plicable	to this \	Vehicle	9		
	1 111001 1 ayıvad 10011			<u> </u>		<u> </u>		<u> </u>	<del></del>							

VEHICLE NO.

		BLE 1-8.						DATE								
L	LRV EQ	UIPMENT	CHECKL	IST								СН	ECK NU	MBERS		J
									1		2	3	4	5	6	7
										ENTRY	RY	RY	RY	RY	RY	RY
NO.									띕	ENJ	LE ENJ	LE	LE ENT	EENT	CE ENT	HICLE II-5 ENTRY
DESCRIPTION AND PART NUMBER		WEIGHT POUNDS W	ARM INCHES x	MOMENT POUND- INCHES Wx	ARM INCHES y	MOMENT POUND- INCHES Wy	ARM INCHES z	MOMENT POUND- INCHES Wz	ON VEHICLE	FORM II-	ON VEHICLE FORM II=5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHIC
CENTERBODY				•												
Valve, Lift Control 7161-472060-1		5.8	157.8	907	200.0	1150	204.0	1173					} }		1 1	
Valve, Emergency Lift Control, 7161-472080-1	(2)	4.9	153.9	751	200.0	976	204.0	996								
Check Valve, LH 7161-472045-1	(/	1.5	146.0	219	188.5	283	209.4	314								
Check, Valve, R4 7161-472045-1		1.5	146.0	219	211.5	317	209.4	314								
Attitude Rocket Cluster, LH Fwd	(4)	6.4	130.0	832	163.8	1048	200.0	1280							]	
Attitude Rocket Cluster, RH Fwd	(4)	6.4	130.0	832	236.2	1512	200.0	1280								
Attitude Rocket Cluster, LH Rear	<b>(4</b> )	6.4	270.0	1728	163.8	1048	200.0	1280		. :						
Attitude Rocket Cluster, RH Rear	(4)	6.4	270.0	1728	236.2	1512	200.0	1280				1				.
Solenoid Valve, LH Fwd 7161-472075	(4)	3.3	130.0	426	168.0	551	200.0	656				1 1				
Solenoid Valve, RH Fwd 7161-472075	<b>(4</b> )	3.3	130.0	426	232.0	761	200.0	656	1 1		<b>}</b>	1 1	1	1	1 1.	1 1
Solenoid Valve, LH Rear 7161-472075	(4)	3.3	270.0	886	168.0	551	200.0	656						1		
Solenoid Valve, RH Rear 7161-472075	(4)	3.3	270.0	886	232.0	761	200.0	656						1 1		
Variable Orifice, LH Fwd, 7161-472110	(4)	3.5	130.0	458	174.8	615	200.0	704								
Variable Orifice, RH Fwd 7161-472110	(4)	3.5	130.0	458	225.2	793	200.0	704	1 1					1		
Variable Orifice, LH Rear 7161-472110 Variable Orifice, RH Rear 7161-472110	(4)	3.5	270.0	950	174.8	615	200.0	704								
Shutoff Valve Electric, LH, 7161-472040	(4)	3.5	270.0	950 645	225.2	793	200.0	704 759								
Shutoff Valve Electric, EH, 7161-472040 Shutoff Valve Electric, RH, 7161-472040		3.7	173.4	645 645	172.8 227.2	643 845	204.0	759 759								
Valve, Motor Operated, Forward 7161-472055		1.3	173.5 153.0	199	200.0	260	204.0	759 270								
Valve, Motor Operated, Forward 7161-472055		1.3	153.0	199	200.0	260	216.0	281			<b> </b>					
Helium Pressure Regulator 7161-472015	(2)	4.2	222.4	943	200.0	848	198.0	840								
Thrust Chamber, Lift, Normal 7161-470001 LH	\ <del>-</del> /	7.4	200.0	1472	166.0	1222	192.5	1417								
Thrust Chamber, Lift, Normal 7161-470001 RH		7.4	200.0	1472	234.0	1722	192.5	1417								
Check Valve, 7161-472070	(2)	3.0	178.0	534	200.0	600	196.7	<b>59</b> 0			]			.		
Plenum Tank, 7161-471020, LH	• •	1.3	219.2	289	166.0	219	207.0	273								
Plenum Tank, 7161-471020, RH		1.3	219.2	289	234.0	309	207.0	273							}	
Relief Valve, 7161-472030 LH		2.8	219.0	613	161.0	451	220.0	616								
Relief Valve, 7161-472030 RH		2.8	219.0	613	239.0	669	220.0	616								
Thrust Chamber 500 lb Emergency LH 7161-4700		22.1	205.0	4532	167.0	3692	192.5	4256						]		
Thrust Chamber 500 lb Emergency RH 7161-4700	001 (3)	22.1	195.0	4311	233.0	5152	192.5	4256								
Actuator, Pitch 7161-390001-1		8.8	190.5	1678	232.9	2052	204.8	1804		-						

VEHICLE NO.

LOCATION AND

ITEM NUMBER

 $\mathbf{B}$ 

B-1

B-2

B-3

B-4

B-5 B-6

B-7

B-8

B-9

B-10

B-11

B-12

B-13

B-14

B-15

B-16

B-17

B-18 B-19

B-20

B-21

B-22

B-23 B-24

B-25

B-26

B-27

B-28

B-29

B - 30

B-31 B - 32

TABLE 1-8. (CONT)
LLRV EQUIPMENT CHECKLIST

	LLRV EQU	JIPMENT (	CHECKLI	ST							CHE	CK NUM	BERS		
				\$ 1 3					1	2	3	4	5	6	7
VEHICL	E NO.	· · · · · · · · · · · · · · · · · · ·				·		· · · · · · · · · · · · · · · · · · ·	ENTRY	E ENTRY	ENTRY	ENTRY	E ENTRY	ENTRY	ENTRY
LOCATION AND ITEM NUMBER	DESCRIPTION AND PART NUMBER	WEIGHT POUNDS W	1 1	MOMENT POUND- INCHES Wx	ARM INCHES y	MOMENT POUND- INCHES Wy	ARM INCHES z	MOMENT POUND- INCHES Wz	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY
В	CENTERBODY (Continued)													-	
B-33 B-34 B-35 B-36 B-37 B-38 B-39	Actuator, Roll 7161-390001-1 Accumulator MS 28700-2 Valve, 3 Way 60600-4 Fuel Flow Proportioner, 25990-1 Accelerometer Installation, RH, 7161-561004 Accelerometer Installation, LH, 7161-561004 Accelerometer Installation, Aft, 7161-561004	8.8 5.4 1.3 2.20 1.7 1.7	174.1 170.6 186.0 221.5 200.0 200.0 238.0	1534 926 242 487 330 330	209.9 200.0 227.1 171.6 237.6 162.4 200.0	1849 1086 295 378 392 268 348	195.6 203.1 202.5 205.0 200.0 200.0 200.0	1723 1103 263 451 330 330 348							
C C-1 C-2 C-3 C-4 C-5 C-6	REAR PLATFORM, FIXED  Drogue Chute, 7161-264002-1, Less bridles Chute Bridles Stowed (4) Helium Tank, LH 7161-471002, Empty Helium Tank, RH 7161-471002, Empty Helium Gas, LH Helium Gas, RH	15.0 3.9 22.3 22.3	275.0 257.1 270.0 270.0 270.0 270.0	4125 1008 6010 <b>6010</b>	215.0 208.2 191.5 208.5 191.5 208.5	3225 816 4263 4641	230.5 229.3 191.5 191.5 191.5	3458 899 4263 4263							
				in the second of											

DATE

# TABLE 1-8. (CONT) LLRV EQUIPMENT CHECKLIST

			•					
	DATE							
				CHE	CK NUM	IBERS		<u> </u>
		1	2	3	4	5	6	7
		- · ·		<del></del>	i		7	
		ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY
		田田田	E	田田田	E S	EN	EN	EN
_		ON VEHICLE FORM II-5 EI	ON VEHICLE FORM II-5 EI	1-5 1-5	ON VEHICLE FORM II-5 EI			
١	MOMENT	M I	M I	M I	M I	/EH M I	M I	MI
3	POUND - INCHES	OR	OR	OR	N OR	N O R	N OR	N N N
1	Wz			0 4	0 4			0 4
	3041 1813 1589 2744 1334 2187 928 209 1588 4112 2594 1356 430 615							
	2624 4642							
			1		1			

									1	2	3	4	5	6	7
									ENTRY	RY	RY	RY	RY.	37	3X
	•								LN	LL	NT	LLN	LLZ		
VEHICLI	E NO							•	ON VEHICLE FORM II-5 EN	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY
	170.		ι,	MOMENIA	T	MOMPATI	T	MOMENT	1 割占	HH	HH	HH	田田山	HELL	
LOCATION AND		WEIGHT	. 1	MOMENT POUND -	ARM	MOMENT POUND-	ARM	MOMENT POUND-	VE ™	V E	V.E.	Υ K E E E E E E	VE ™	ME	VE.
ITEM	DESCRIPTION AND PART NUMBER	POUNDS		INCHES ·	INCHES	INCHES	INCHES	INCHES	zjo	ZÖ	ZÖ	ZÖ	z ő	ZO	z
NUMBER		W	x	Wx	y	Wy	z	Wz				0 4			
D	REAR PLATFORM, MOVABLE 3				1	<u> </u>						1			11
								20.44				-			
D-1	Avionics Rack Structure, 17-09680	13.6	325.9	4432	193.4	2630	223.6	3041	<u> </u>					1	
D-2	Power Amplifier 17-09550-1	8.3	325.6	2702	187.7	1558	218.4	1813					1		
D-3	Weight and Drag Computer 17-09570-1	6.8	325.6	2214	198.5	1350	233.7	1589			1 1	1			
D-4	Monitor 17-09590-1	12.1	325.6	3950	197.1	2391	226.2	2744							
D-5	Auto Throttle 17-09500-1	5.9	326.6	1927	186.4	1100 1 <b>973</b>	226.2 218.7	1334 2187					1	1	
D-6	Input and Summation 17-09580-1	10.0	325.6	3256	197.3		ł I					1			
D-7	ACS Adjustment Potentiometer Package, 17-09610-1	4.4	329.6	1450	197.2	868	211.0	928							
D-8	Transformer 17-09539-1	1.0	325.0	325	184.8	185	209.4	209							
D-9	Emergency Inverter	7.6	323.0	2455 5429	186.0 191.0	1414 3744	209.0	1588 <b>4112</b>					1 1		
D-10	Gyro Package, 17-09720	19.6	277.0 325.6	3614	188.7	2094	233.7	2594						.	
D-11 D-12	Jet Stab Amplifier 17-09520-1	11.1	1	1886	i 1		226.0				1	1			
D-12 D-13	Battery, 7161-202002-1	6.0	314.3 314.4	604	187.5 195.5	1125 375	224.0	1356 <b>430</b>		[					
D-13 D-14	Voltage Regulator CSV-1178-1 Power Shield 7161-203001-1	1.9 2.8	315.2	879	191.0	533	220.5	615							
D-14 D-15	Power Smeld 7101-203001-1	2.0	313.2	019	191.0	JJJ	220.5	010		1 1				1	
D-13 D-16															
D-17 🔼	PCM Telemetry Transmitter	15.0	320.0	4800	214.0	3210	211.5	3173							
D-18 🔼	DC Signal Conditioner	7.0	314.0	2198	211.0	1477	211.0	1477							
D-19 🔼	AC Signal Conditioner	6.0	314.0	1884	216.0	1296	211.0	1266							
D-20 🔼	Power Supply	7.0	316.0	2212	207.0	1449	211.0	1477		1			1 1		
D-21 🔼	Radar Altimeter Control	9.2	314.5	2893	191.0	1757	211.5	1946			1				
D-22 🔼	Radar Altimeter Transmitter	5.6	314.0	1758	210.0	1176	199.0	1114						1 1	
D-23 🔼	Radar Altimeter Receiver	2.9	328.5	953	210.0	609	200.0	580							
D-24 🔼	Radar Altimeter Data Converter	2.0	326.5	653	208.5	417	209.0	418		1				1	
D-25 🔼	Doppler Receiver Transmitter	13.3	326.0	4320	191.0	2531	198.0	2624							
D-26 🔼	Doppler Converter	22.0	320.0	7040	203.0	4466	211.0	4642							
/3\	All centers of gravity are with the movable items in th	 e full down	! , full aft,	central positi	ion										
	NASA payload item.	ļ	•	-											

# TABLE 1-8. (CONT) LLRV EQUIPMENT CHECKLIST

	LLKV EN	UIPMENT	CHECKL	191						ele e e e e e e e e e e e e e e e e e e	СНЕ	CK NUM	BERS		
									1	2	3	4	5	6	7
VEHICI	E NO.	<u>-</u>			·				LE ENTRY	LE ENTRY	LE ENTRY	LE ENTRY	LE ENTRY	CE ENTRY	LE ENTRY
LOCATION AND ITEM NUMBER	DESCRIPTION AND PART NUMBER	WEIGHT POUNDS W	5 4	MOMENT POUND- INCHES Wx	ARM INCHES	MOMENT POUND- INCHES Wy	ARM INCHES	MOMENT POUND- INCHES Wz	ON VEHICLE FORM II-5 EN	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY
E	GIMBAL RING AND POWER PLANT 6								1						1-1-1
E-1 E-2 E-3 E-4 E-5 E-6 E-7 E-8 E-9 E-10 E-11 E-12 E-13 E-14 E-14 E-15 E-16 E-17	Compressor Inlet 7161-421036 Engine, CF 700-2V, Basic Dry Generator DGH-245-1 Inverter 1518-8-B Reverse Current Relay AN3025-300 Tachometer 7161-434012-1 Auto Throttle Control 17-08250-1 Hydraulic Pump 7161-390002-1 Hydraulic Reservoir 7161-390003-1 Hydraulic Fluid (Reservoir Full) Hydraulic Filter MS28896-4 Gimbal Lock - Pitch Gimbal Lock - Roll Screen - Compressor Inlet 7161-880002 Screen - Fan Inlet 7161-880003 Cover, Compressor Inlet, 7161-880007-1 Cover, Fan Inlet, 7161-880001-3,5,7, and 9 (4)	5.6 628.0 30.7 33.0 2.7 0.8 6.9 1.8 1.5 3.0 0.8	199.6 199.7 205.7 205.2 211.0 196.5 186.7 205.6 212.3 212.3 217.0	1092 125,412 6315 6764 579 157 1292 370 319 637 163	199.6 199.0 188.1 212.0 188.2 188.1 191.5 188.1 188.2 193.8	1093 124,972 5775 6992 517 150 1325 338 282 565 145	230.7 197.6 226.2 212.6 214.0 210.2 214.7 214.0 220.0 186.8	1264 124,093 6944 7012 588 168 1486 385 330 660 140							
	All centers of gravity are with the engine vertical and on NASA payload item.  Ground support equipment.	exerting 1g	thrust.												

# TABLE 1-8. (CONT) LLRV EQUIPMENT CHECKLIST

DATE							
			CHE	CK NUM	BERS	I <u>., </u>	
	1	2	3	4	5	6	7
	TRY	TRY	TRY_	FRY	rry	rry	ľRY
	LE EN	LE EN	LE EN	EE	EN	EN	ENJ
MOMENT POUND- INCHES Wz	ON VEHICLE FORM II- 5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY
3006 3390 7164 7164 4926 2908 273 2741 4926 2908 273 2741 4926 2908 273 2741 4926 2908 273 2741 112							

	O Sea A Marie	II MILINI O	III OILIIL	, 1					1	2	3	4	5	6	7
									'nŸ	RY	RY	RY	RY	RY	RY
VEHICLE	NO.				:				LE 5 ENTRY	LE	LE ENT	LEENT	HICLE II-5 ENTRY	LEENT	LEENT
LOCATION AND ITEM NUMBER	DESCRIPTION AND PART NUMBER	WEIGHT POUNDS W	1 1	MOMENT POUND- INCHES Wx	ARM INCHES y	MOMENT POUND- INCHES Wy	ARM INCHES z	MOMENT POUND- INCHES Wz	ON VEHICLE FORM II-5 EN	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY	ON VEHIC FORM II-5	ON VEHICLE FORM II-5 ENTRY	ON VEHICLE FORM II-5 ENTRY
F	TRUSS LEGS AND MISCELLANEOUS														
F-1 F-2 F-3 F-4 F-5 F-6 F-7 F-8 F-9 F-10 F-11 F-12 F-13 F-14 F-15 F-16 F-17 F-18 F-19 F-20 F-21	Strut Installation RH Forward 7161-191005-1 Strut, 7161-191006-1 Pad 7161-191002-1 Caster Assy RH Forward 7161-191005-5 Strut Installation, RH Rear 7161-191005-1 Strut 7161-191006-1 Pad 7161-191002-1	16.0 16.0 35.8 35.8 34.9 20.0 2.3 24.6 34.9 20.0 2.3 24.6 34.9 20.0 2.3 24.6 34.9 20.0	146.1 253.9 200.0 200.0 119.9 119.9 119.9 280.1 280.1 280.1 119.9 119.9 119.9 1280.1 280.1 280.1 280.1 280.1 280.1 280.1	2336 4059 7164 7164 4185 2397 279 2949 9783 5603 653 6894 4185 2397 279 2949 9783 5603 653 653 6894 110	200.0 200.0 148.5 251.5 119.9 119.9 119.9 119.9 119.9 280.1 280.1 280.1 280.1 280.1 280.1 280.1 280.1 280.1	3198 3198 5319 9009 4185 2397 279 2949 4185 2397 279 2949 9783 5603 653 6894 9783 5603 653 6894 146	188.0 212.0 200.0 200.0 141.1 145.4 117.0 111.4 145.4 117.0 111.4 145.4 117.0 111.4 145.4 117.0 111.4 145.4 117.0	3006 3390 7164 7164 4926 2908 273 2741 4926 2908 273 2741 4926 2908 273 2741 4926 2908 273 2741 4926 2908 273 2741							
	Including subsequent indented items.  Centers of gravity with strut at full extension.  Ground support equipment.														

Report 7161-954002

## SECTION II

# ACTUAL WEIGHING DATA

# 2.1. GENERAL INFORMATION.

Weighing of this vehicle is accomplished in four separate operations. Extreme care must be taken in measuring the actual weight and balance of the LLRV in order to assure that the CG limits discussed in Paragraph 1.3. are not exceeded. These operations include:

- (a) Weight and center of gravity determination of the center of gravity fixture.
- (b) Weight and vertical center of gravity determination of the jet engine assembly, gimbal ring, and associated equipment.
- (c) Weight and horizontal center of gravity determination of the center of gravity fixture and gimballed equipment.
- (d) Weight and center of gravity determination of the complete vehicle mounted on the center of gravity fixture.
- 2.2. WEIGHT AND CENTER OF GRAVITY DETERMINATION OF THE CENTER OF GRAVITY FIXTURE.
- 2.2.1. Description. The LLRV Center of Gravity Fixture, part number 7161-700001, is shown in Figure 2-1. The fixture consists of the following five major components and three sets of attachment hardware.

## 2.2.1.1. Major Components. -

Support truss assembly (one)

Weighing scales (three, not supplied)

Engine mount plates (three)

Master ring (one)

Spacers (three)

2.2.1.2. Support Truss Assembly. - The support truss assembly consists of a reinforced triangular base plate 95 inches long and 109 inches wide to which are attached three eight-inch diameter swivelling casters. The base plate provides a support for three 1-3/4-inch diameter adjustment screws and a tubular welded truss framework. The top of the truss framework is welded to a 46-1/4-inch diameter retaining ring having a depth of 3-3/4 inches. Permanently fastened to this ring are three welded mount fittings for attachment

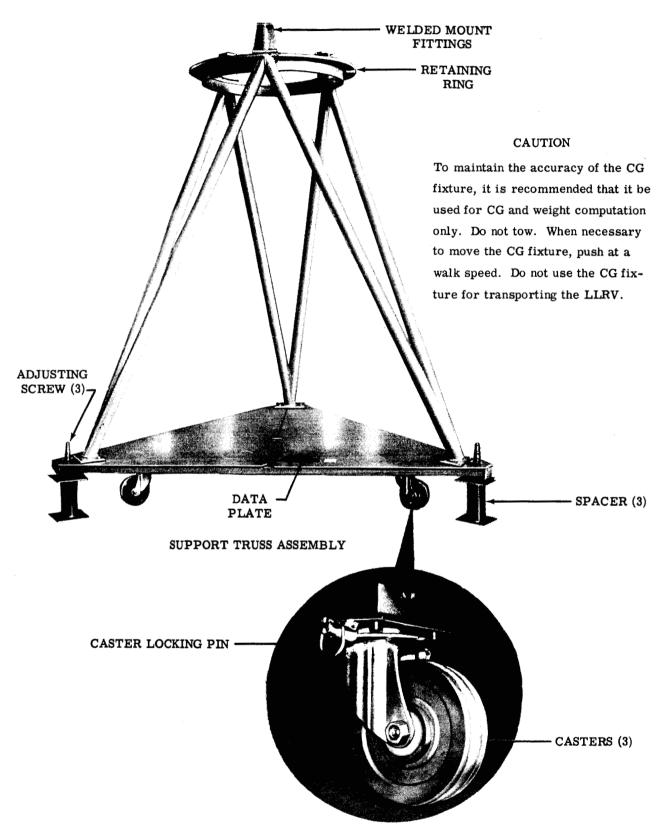


Figure 2-1. Center of Gravity Fixture

of the LLRV. These fittings are six inches square at the base, four inches square at the top with a height of eight inches. The 3/4-inch thick top plates of the fittings are drilled for attachment bolts and are machined so that their top surfaces lie in one plane.

The overall dimensions of the support truss assembly are length, 95 inches; width, 109 inches; and height, 119 inches. The weight is approximately 1000 pounds.

- 2.2.1.3. Engine Mount Plates The engine mount plates, shown in Figure 2-2, are to be attached to the LLRV engine mount at three points and are employed to adapt and position the vehicle on the center of gravity fixture. The plates are three inches square and 3/4 inch thick with four 5/16-inch holes and one 1/2-inch tapped hole for attachment bolts. A 5/8-inch diameter centering pin is also provided in each plate.
- 2.2.1.4. <u>Master Ring.</u> The master ring, shown in Figure 2-3, is employed as a template to accurately position the engine mount plates with respect to the main engine mounts. It is also used during fixture assembly to accurately locate the mount fittings of the support truss assembly. The master ring is fabricated of 1/2-inch aluminum plate with an outside diameter of 56 inches and an inside shape contoured for clearance with the LLRV engine. Two tangs are provided on the inside of this ring for attachment to the unused main mounts of the LLRV jet engine. Three accurately located 5/8-inch inside diameter bushings are provided for positioning the three engine mount plates. Two captive 7/16-inch diameter bolts are provided for attaching the ring to the main engine mounts. Identification notes are provided on the master ring to indicate the correct installation directions.
- 2.2.1.5. Spacers. Three 10-1/4-inch high spacers are provided to adapt the fixture to a flush mounted floor scale installation.

## 2.2.1.6. Attachment Hardware. -

Master ring attachment pins (two, part number 7161-421028-1)

Engine mount plate attachment bolts (twelve, NAS674-16H)

LLRV mounting screws (four, 1/2-inch diameter socket head cap screws with warning streamers)

# 2.2.2. Procedure. -

Step 1. Obtain three scales of at least 500-pound capacity and accurate within ±0.25 pound. Ensure that the scales are correctly calibrated and levelled. Establish scale zero errors.

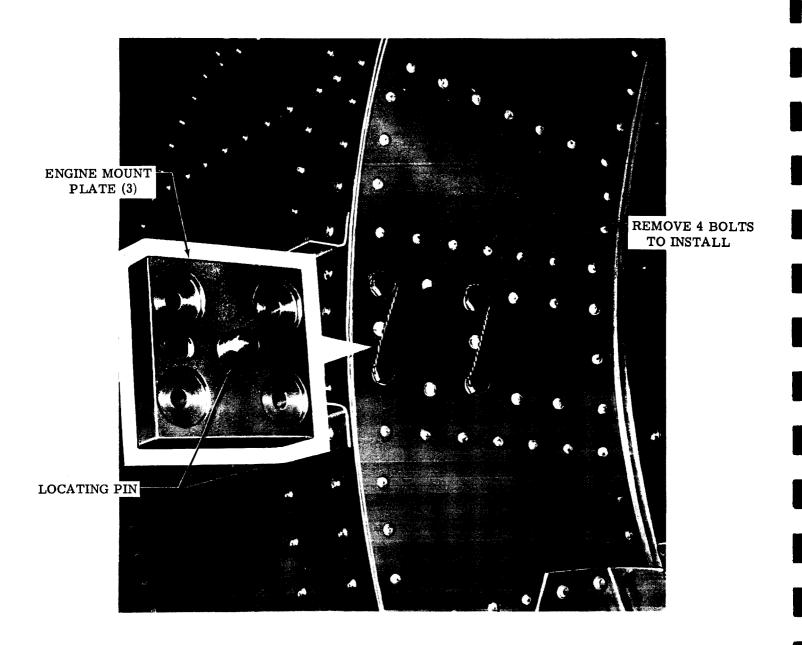
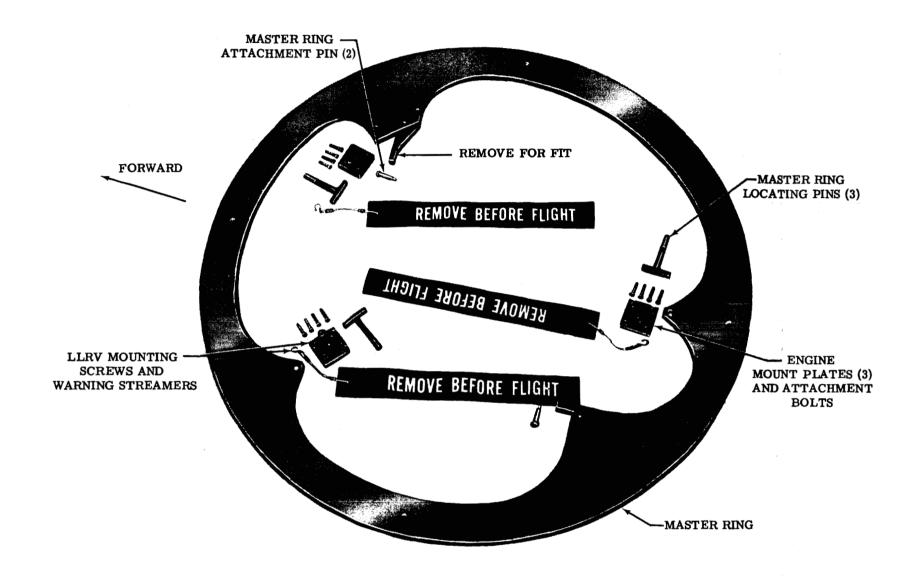


Figure 2-2. Engine Mounting Detail



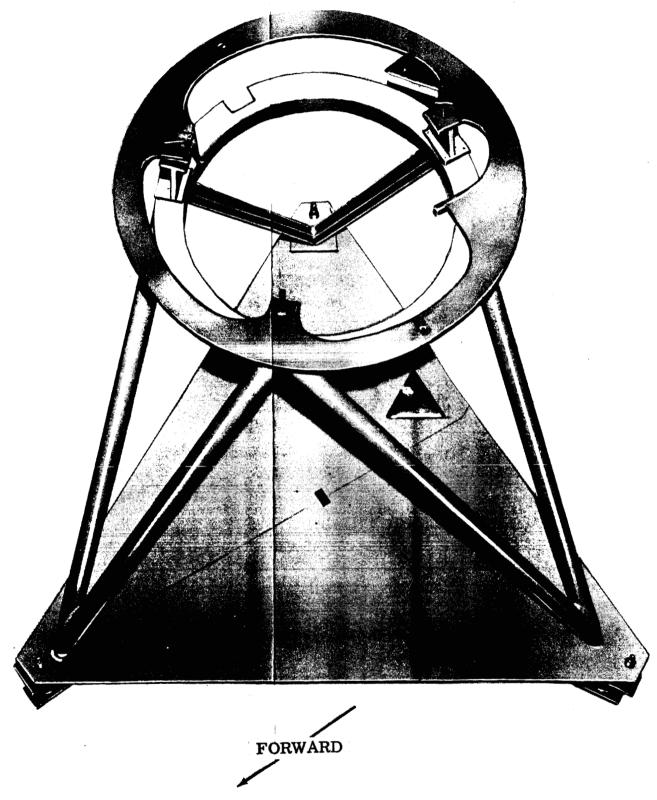


Figure 2-3. Master Ring

Step 2. Position the three scales under the 1-3/4-inch adjusting screws, located at each corner of the support truss assembly triangular base. Scales should be located so that the adjusting screws are as close as possible to the center of the weighing platform.

### NOTE

When a flush scale installation is used, it will be necessary to position the support truss assembly over the platforms, then locate the 10-1/4-inch spacers under the adjusting screws.

Step 3. Transfer the weight of the support truss assembly from the casters to the weighing scales by turning the adjusting screws. Lock the support truss assembly casters.

### CAUTION

The casters must be locked in the same position for each weighing exercise to insure consistent results.

Step 4. Loosely attach the engine mount plates to the engine mount fittings using the NAS674-16H bolts. Loosely install the three 1/2-inch diameter socket head cap screws with warning streamers.

# NOTE

This hardware is required to attach the engine mount to the fixture and is not part of the vehicle. Its weight must therefore be included with that of the center of gravity fixture.

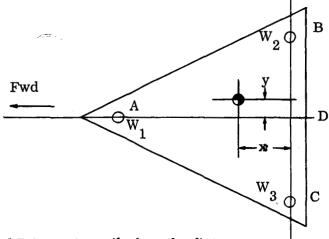
Step 5. Level the support truss assembly in the lateral and longitudinal planes using the adjustment screws and a clinometer applied to the top support ring fittings. Access to the fittings will require a ladder or a maintenance stand.

A Hilger and Watts No. 75022 Clinometer or its equivalent having an accuracy of ±5.0 minutes is recommended.

- Step 6. Record scale readings on Weighing Record Form II-1, sheet 1.
- Step 7. Unlock the casters. Transfer the weight of the fixture from the scales to the casters by turning the adjustment screws. Remove the platform scales or the 10-1/4-inch spacers if a flush weighing facility is used, and move the fixture off the platforms. Recheck the scales for zero errors. Record all results as required using the Weighing Record Form II-1.
- Step 8. As a check on accuracy, repeat Steps 2, 3, 5, and 6. The fixture should be rotated so that each leg now stands on a different scale. Upset the beam on each scale and take the mean of several readings. When the weight and center of gravity of the fixture are obtained, they should be marked on the fixture for permanent reference.
- Step 9. Locate the fixture center of gravity by taking moments. (See diagram and Weighing Record Form II-1, sheets 1 and 2.)

$$x = \left(\frac{W_1 \times AD}{W_1 + W_2 + W_3}\right) \text{ inches}$$

$$y = \left(\frac{W_2 BD - W_3 CD}{W_1 + W_2 + W_3}\right) inches$$



Dimensions AD, BD, and DC are inscribed on the fixture.

# WEIGHING RECORD

# CENTER OF GRAVITY FIXTURE

DATE	PLACE			WEIGHED BY
JACKPOINT	SCALE READING	TARE	NET WEIGHT	
A			$w_1$	J <sub>B</sub>
В			$w_2$	W <sub>2</sub>
С			$w_3$	Fwd A E D
Total as Weighed				w <sub>3</sub> <b>0</b> c

MEASUREMENTS (Inscribed on fixture)

AD = \_\_\_\_inches, the distance from jackpoint A to BC

BD = \_\_\_\_ inches, the distance from jackpoint B to AD

DC = \_\_\_\_inches, the distance from jackpoint C to AD

ED = \_\_\_\_ inches, the distance from BC to the projected engine vertical centerline

# CENTER OF GRAVITY CALCULATIONS

x = distance of center of gravity from BC

y = distance of center of gravity from AD

$$x = \left(\frac{W_1 \times AD}{W_1 + W_2 + W_3}\right)$$
 inches = \_\_\_\_\_ inches

$$y = \left[ \frac{(W_2 \times BD) - (W_3 \times CD)}{W_1 + W_2 + W_3} \right] \text{ inches}$$
 inches

# WEIGHING RECORD

# CENTER OF GRAVITY FIXTURE

Convert centers of gravity x and y to vehicle body stations X and buttock lines Y.

BS 
$$X = (200 + ED - x)$$
 inches = \_\_\_\_\_ inches

BL Y = 
$$(200 \pm y)$$
 inches = \_\_\_\_\_ inches

Determine the correct sign for y by comparing the values of  $\boldsymbol{W}_2$  and  $\boldsymbol{W}_3$ .

If 
$$W_3 > W_2$$
, y is negative

If 
$$W_2 > W_3$$
, y is positive

If 
$$W_2 = W_3$$
, y is zero

- 2.3 WEIGHT AND VERTICAL CENTER OF GRAVITY DETERMINATION OF THE JET ENGINE ASSEMBLY, GIMBAL RING, AND ASSOCIATED EQUIPMENT.
- 2.3.1. General. All items supported within the gimbal pitch bearings must be weighed and have their center of gravity determined before being installed in the vehicle. This procedure assumes that the jet engine is supported in a Model 3100 Air Logistics Workstand (Figure 2-4) or an equivalent parallel rail equipment.

# 2.3.2. Procedure. -

- Step 1. Obtain a suitable set of calibrated scales and ensure that they are level.

  Establish scale zero errors. If platform scales are to be used, four, with a capacity of 300 to 500 pounds each will be required. Flush type floor scales are preferable and should be used if available.
- Step 2. Ensure that the jet engine assembly is securely locked in the Supporting Frames (part number 7161-752002).

### NOTE

The hydraulic reservoir and engine oil tank must be drained before the jet engine assembly is rotated into the horizontal position.

- Step 3. Using the hoist rings provided, position the workstand on the scales. Check the attitude of the workstand by using a clinometer on the upper surface of the rail and shim under the legs to bring the stand to the level position within ±0.5 degree. Check the jet engine assembly attitude by using a clinometer on a suitable area of the casing. The power plant should be levelled to within ±0.5 degree.
- Step 4. Note the scale readings. Obtain a mean of at least three readings, upsetting the beam between each reading.
- Step 5. Immediately after weighing, measure the distances between the scale reaction points. On the four legged workstand, measure both sides and use the mean value. Using a plumb bob and tape measure (or other suitably accurate method), locate the jet engine assembly mounting lugs with respect to the

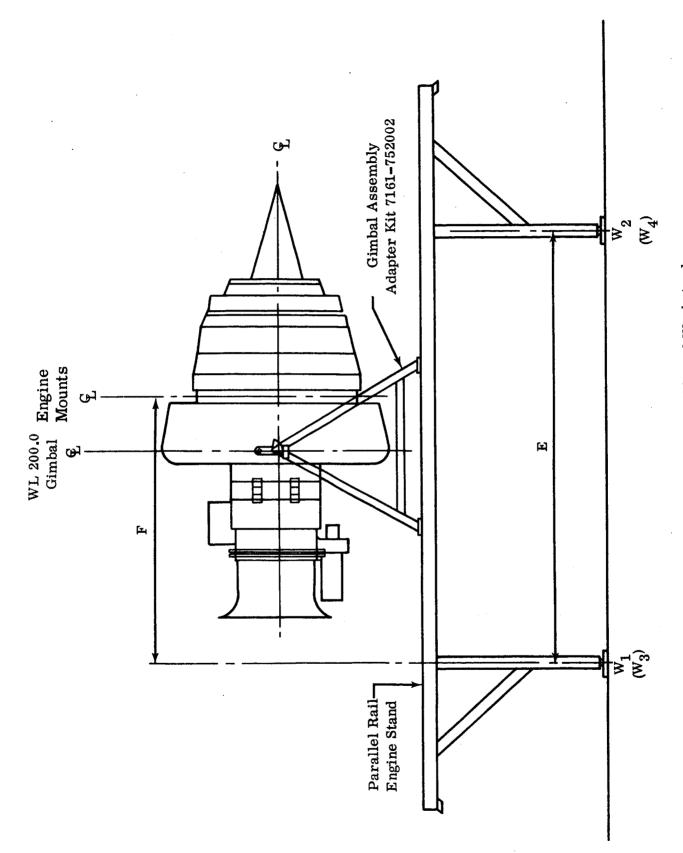


Figure 2-4. Jet Engine Assembly and Workstand

- scale contact points. Determine the combined center of gravity of the jet engine assembly and workstand by taking moments.
- Step 6. Repeat Steps 1 through 5 on the workstand and adapter kit. Remove the workstand from the scales and recheck for zero errors.
- Step 7. By subtraction, obtain the weight and center of gravity of the jet engine assembly package. Convert the jet engine assembly center of gravity to a vehicle waterline value. (Refer to Bell Aerosystems Company's drawing No. 7161-421001.)
- Step 8. Weigh the assembled gimbal ring. The center of gravity of this unit is at Station 200.0 in all three axes. Add the weight and moment of the gimbal ring to the jet engine assembly. Make whatever adjustments are necessary for missing or extra items and obtain the weight and center of gravity of the complete gimballed assembly. Record results for use when weighing the complete vehicle.
- Step 9. Weighing Record Forms similar to Form II-2 should be used to facilitate computations.

# WEIGHING RECORD GIMBALLED EQUIPMENT

DATE	PI	ACE		WEIGHED BY						
	A. GIM	BALLED EQUIP	MENT AND	WC	DRKSTAND					
ENGINE NO.		STAND NO.			TYPE OF SCALES USED					
ENGINE ATTITUD	E °	STAND ATTITI	UDE	٥						
REACTION	SCA	LE READING	TARE	N	ET WEIGHT					
Fwd Leg A				,	$\mathbf{w_1}$					
Fwd Leg B										
Rear Leg C					***					
Rear Leg D	_				$\mathbf{w}_{2}$					
Total as Weighed										

# MEASUREMENTS

 $E = \underline{\hspace{1cm}}$  inches, the mean distance between scale reaction points  $F = \underline{\hspace{1cm}}$  inches, the distance between the engine mount centerline and forward scale reaction point

# CENTER OF GRAVITY CALCULATIONS

x = distance of center of gravity from forward scale reaction point

$$x = \left(\frac{W_2 \times E}{W_1 + W_2}\right)$$
 inches = \_\_\_\_\_ inches

# WEIGHING RECORD

# GIMBALLED EQUIPMENT

# B. WORKSTAND AND ENGINE SUPPORTS

STAND ATTITUDE	Ö	STAND NO.		SCALES USED
REACTION	SCALE	READING	TARE	NET WEIGHT
Fwd Leg A				11/
Fwd Leg B				$W_3$
Rear Leg C				117
Rear Leg D				${ m W_4}$
Total as Weighed				

# CENTER OF GRAVITY CALCULATIONS

y = distance of workstand center of gravity from forward scale reaction point

$$y = \left(\frac{E W_4}{W_3 + W_4}\right)_{inches} =$$
 inches

z = distance of gimballed equipment center of gravity from forward scale reaction point.

$$z = \left(\frac{x (W_1 + W_2) - y (W_3 + W_4)}{(W_1 + W_2) - (W_3 + W_4)}\right)_{\text{inches}} = \underline{\qquad}_{\text{inches}}$$

Weight of gimballed equipment =  $(W_1 + W_2) - (W_3 + W_4) =$ \_\_\_\_\_pounds.

Knowing distances F and z, convert the gimballed equipment center of gravity to vehicle waterline Z.

BASIC WEIGHT AND VERTICAL CENTER OF GRAVITY OF GIMBALLED EQUIPMENT

GIMBALLED EQUIPMENT

Form II-2

LED EQUIPMENT WEIGHT N WEIGHED POUNDS N WEIGHED POUNDS	COLUMN I	N I		согими п			
		WEIGHT	 MOMENT WZ POUND-INCHES	BASIC ITEMS NOT ON GIMBALLED EQUIPMENT WHEN WEIGHED		VERT ARM Z INCHES	MOMENT WZ POUND-INCHES
					-		
						-	And the second designation and the second se
						-	
		-					
				And the state of t	-		
		-					
The state of the s							
Total	abenderally entre and the fact of the fact	The second secon		Total			

DESCRIPTION	NET WEIGHT POUNDS W	VERT ARM Z INCHES	MOMENT WZ POUND-INCHES
Total as Weighed $(W_1 + W_2) - (W_3 + W_4)$			
Engine Oil	+		+
Hydraulic Oil	+		+
Gimbal Ring	+		+
		-	
Total Col. I Items	1		
Total Col. II Items	+		+
Basic Weight			
		ſ	

Enter this basic weight, arm, and moment in the Gimballed Equipment Basic Weight and Balance Record, Form II-4.

2-15/2-16

Report 7161-954002

- 2.4 WEIGHT AND HORIZONTAL CENTER OF GRAVITY DETERMINATION OF THE CENTER OF GRAVITY FIXTURE, JET ENGINE ASSEMBLY, GIMBAL RING, AND ASSOCIATED EQUIPMENT.
- 2.4.1. Preparation for Weighing. -
  - Step 1. Determine the weight and lateral centers of gravity of the center of gravity fixture as described in Paragraph 2.2.
  - Step 2. Determine the weight and vertical center of gravity of the gimballed equipment as described in Paragraph 2.3.
  - Step 3. Obtain three suitable scales. Ensure that the scales are correctly calibrated and levelled.
  - Step 4. Position and level the fixture as described in Paragraph 2.2.2., Steps 2 through 5.
  - Step 5. Note scale readings and compare with figures obtained when the fixture was last weighed. If there is a discrepancy, determine the cause and rectify before proceeding.
- 2.4.2 Procedure for Positioning the Jet Engine Assembly on the Center of Gravity
  Fixture.-
  - Step 1. Turn the engine to the vertical position in the workstand. Service the oil and hydraulic systems if necessary.
  - Step 2. Using an overhead hoist, lower the Vertical Sling Assembly, Part Number 7161-753001-1, over the engine. Remove four pins, Part Number VP9STS5S17T5H4C, from the hoist sling fittings. Position the hoist sling fittings over the engine mount roll fittings at waterline 199.625 and insert the pins, locking them in position.
  - Step 3. Raise the hoist sufficiently to take the slack out of the hoisting cables. Remove four AN7-11A bolts from each adapter kit flange, Part Number 7161-752002-29, and lift on the hoist to disengage the engine assembly from the workstand. If the engine shows a tendency to rotate in the hoist, the location of the Fitting Bracket, Part Number 7161-753001-13, should be adjusted.

- Step 4. Remove twelve NAS674-4H bolts from the bottom side of the LLRV engine mount. These bolts are located as follows:
  - (a) Four centered about a point 14.387 inches forward of the engine and 14.205 inches to the right side.
  - (b) Four centered about a point 14.387 inches forward of the engine and 14.205 inches to the left side.

### CAUTION

Do not remove the seven 3/16-inch diameter bolts found in the same general area.

- (c) Four centered about a point on the LLRV longitudinal axis and 20.218 inches aft of the lateral engine centerline.
- Step 5. Loosely attach three engine mount plates with centering pins pointing down to the locations described in Step 4 using twelve NAS674-16H bolts. The engine mount plates consist of two Part Number 503 and one Part Number 502. Part Number 502 has shorter hole spacings and should be located at the most aft mounting point (location (c) in Step 4 above).
- Step 6. Remove large tang from master ring (at engine mount location) and position the master ring beneath the LLRV engine so that the areas stamped FWD and USE AGAINST VEHICLE are properly oriented with respect to the LLRV.
- Step 7. Raise the master ring up and around the LLRV engine assembly until the aft tang on the inside diameter of the ring engages the unused aft main engine mount slot. Replace and engage the forward tang in the forward right engine mount slot. During this operation, the spherical ends of the centering pins in the loosely attached engine mount plates are inserted into appropriate positioning holes of the master ring.
- Step 8. Attach master ring to LLRV engine using two captive pins, Part Number 7161-421028-1, inserted through the ring tangs and main engine mounts.
- Step 9. Tighten the twelve NAS674-16H bolts in the engine mount plates.

- Step 10. Remove the large tang from the master ring and remove the master ring from the engine assembly. Replace tang on master ring. Ensure that the support truss is properly oriented with the FWD notation on the triangular base corresponding to forward on the engine assembly.
- Step 11. Using the overhead hoisting device, lift and then lower the engine onto the center of gravity fixture until the centering pins of the engine mount plates slip into the alignment holes of the mount fittings attached to the top ring of the support truss assembly.

### **CAUTION**

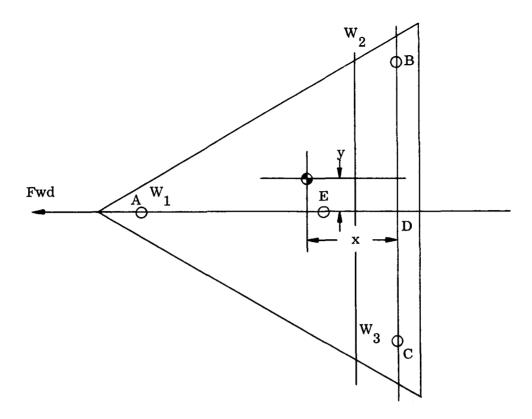
Proceed with extreme care when lowering the engine to assure that clearances exist between components and the fixture and that no damage occurs as the alignment pins engage the mount fittings.

- Secure the engine to the center of gravity fixture by installing three

  1/2-inch diameter socket head cap screws with the warning streamers up
  through the top of the mount fittings and into the engine mount plates.
- Step 13. Remove the engine vertical hoist sling.
- 2.4.3 Weighing Procedure. -
  - Step 1. Record the scale readings as shown on the sample Weighing Record Form II-3.
  - Step 2. Repeat the readings as necessary to ensure accuracy, upsetting the scale beams between subsequent readings. When the fixture is removed, check the scale zero errors and record all results as required. (See Form II-3.)
  - Step 3. Locate the combined center of gravity of the engine assembly and the fixture by taking moments:

$$x = \left(\frac{W_1 \times AD}{W_1 + W_2 + W_3}\right) \text{inches}$$

$$y = \left(\frac{W_2 BD - W_3 CD}{W_1 + W_2 + W_3}\right) inches$$



Dimensions AD, BD and DC are inscribed on the fixture

# 2.4.4. Procedure for Removing the Jet Engine Assembly from the Center of Gravity Fixture. -

Step 1. Using the overhead hoisting device, lower and position the engine vertical sling assembly and attach the sling fittings to the engine mount roll fittings using the pins provided.

### **CAUTION**

Do not attempt to raise the engine at this time as severe damage to the engine mount may result. The hoist sling is attached at this time to eliminate possible tipping and subsequent damage to the engine during scale and fixture removal operations.

Step 2. Unlock the casters. Transfer the weight of the fixture and engine assembly

### GIMBALLED EQUIPMENT AND CENTER OF GRAVITY FIXTURE

DATE	PLACE	Wi	EIGHED BY
ENGINE NO.	SCALES	USED	
JACKPOINT	SCALE READING	TARE	NET WEIGHT
A			w <sub>1</sub>
В			W <sub>2</sub>
C			W <sub>3</sub>
Total as Weighed			

MEASUREMENTS	(Inscribed	on	fixture)	
--------------	------------	----	----------	--

AD = \_\_\_\_ inches, the distance from jackpoint A to BC \_\_\_\_\_

BD = \_\_\_\_\_ inches, the distance from jackpoint B to AD

DC = \_\_\_\_\_ inches, the distance from jackpoint C to AD

DE = \_\_\_\_\_ inches, the distance from BC to the projected engine vertical centerline

### CENTER OF GRAVITY CALCULATIONS

x = distance of center of gravity from BC

y = distance of center of gravity from AD

$$x = \left(\frac{W_1 \times AD}{W_1 + W_2 + W_3}\right)_{inches} = \underline{\qquad} inches$$

$$y = \left(\frac{(W_2 \times BD) - (W_3 \times CD)}{W_1 + W_2 + W_3}\right)_{\text{inches}} = \underline{\qquad}_{\text{inches}}$$

Locate the center of gravity with respect to AD by comparing  $\boldsymbol{W}_2$  and  $\boldsymbol{W}_3.$ 

### GIMBALLED EQUIPMENT AND CENTER OF GRAVITY FIXTURE

# COMBINED WEIGHT AND CENTER OF GRAVITY OF FIXTURE AND BASIC GIMBALLED EQUIPMENT

Convert centers of gravity x and y to vehicle Body Stations (X), and Buttock Lines (Y).

BS 
$$X = (200 + ED - x)$$
 inches = \_\_\_\_\_ inches

BL 
$$Y = (200 \pm y)$$
 inches = \_\_\_\_\_ inches

Determine the correct sign for y by comparing the values of  $\boldsymbol{W}_2$  and  $\boldsymbol{W}_3$ .

If  $W_3 > W_2$ , y is negative

If  $W_2 > W_3$ , y is positive

If  $W_2 = W_3$ , y is zero

		CO	LUMN I		
ITEMS WEIGHED BUT NOT PART OF BASIC GIMBALLED EQUIPMENT	WEIGHT POUNDS W	ARM x INCHES	MOMENT Wx POUND-INCHES	ARM y INCHES	MOMENT Wy POUND-INCHES
Total Col. I					

### GIMBALLED EQUIPMENT AND CENTER OF GRAVITY FIXTURE

		COL	UMN II	, , <del></del> <del></del>	
BASIC ITEMS NOT ON GIMBALLED EQUIPMENT WHEN WEIGHED	WEIGHT W POUNDS	ARM x INCHES	MOMENT Wx POUND-INCHES	ARM y INCHES	MOMENT Wy POUND-INCHES
Total Column II					

DESCRIPTION	WEIGHT W POUNDS	ARM x INCHES	MOMENT Wx POUND-INCHES	ARM y INCHES	MOMENT Wy POUND-INCHES
Total as Weighed (from Sheets 1 and 2)					
Gimbal Ring	+	200.0	+	200.0	+
Engine Oil					
Hydraulic Oil					
Total Col. I Items	_		<del>-</del>		-
Total Col. II Items	+		+		+
Fixture and Basic Gimballed Equipment Total					

### GIMBALLED EQUIPMENT AND CENTER OF GRAVITY FIXTURE

# DETERMINATION OF LATERAL CENTERS OF GRAVITY OF GIMBALLED EQUIPMENT

DESCRIPTION	WEIGHT W POUNDS	ARM x INCHES	MOMENT Wx POUND-INCHES	ARM y INCHES	MOMENT Wy POUND-INCHES
Fixture and Basic Gimballed Equipment (Form II-3, Sheet 3)					
Fixture (Form II-1, Sheets 1 and 2)	-		-		-
Basic Gimballed Equipment					

Compare this weight of the basic gimballed equipment with that obtained in Form II-2, sheet 3. The two should agree.

Enter this weight on the Gimballed Equipment Basic Weight and Balance Record, Form II-4.

Form II-4

BASIC WEIGHT AND BALANCE RECORD

# GIMBALLED EQUIPMENT

CONTINUOUS HISTORY OF CHANGES IN STRUCTURE OR EQUIPMENT AFFECTING WEIGHT AND BALANCE

ENGINE NO.

		WEIGHT AN	TD MOME	NT CHANG	ES AND I	SUNNING T	OTAL BA	SIC WEIGHT
		WEIGHT	ARM	MOMENT Wx	ARM	MOMENT ARM Wy	ARM	WEIGHT ARM WX ARM WY ARM WZ
DATE	COMPLETE DESCRIPTION OF CHANGE	w POUNDS	x INCHES	POUND- INCHES	y INCHES	POUND- INCHES	z INCHES	POUND-
		-						
		,						

from the scales to the casters by turning the adjusting screws. Remove the scales or the 10-1/4-inch spacers if a flush weighing facility is used.

Step 3. Remove three 1/2-inch diameter socket head cap screws and warning streamers. These screws attach the LLRV engine mount plates to the mount fittings of the CG fixture.

### CAUTION

Do not under any circumstances attempt to hoist the engine without first removing the three 1/2-inch diameter screws. Serious damage to the engine mount could occur if the engine is hoisted while still attached to the fixture.

Step 4. Using the overhead hoisting device, carefully raise the engine out of the CG fixture to a point where the engine exhaust cone will clear the top fittings of the truss.

### CAUTION

Proceed with extreme care when raising the engine out of the fixture to assure that clearances exist between engine components and the fixture.

- Step 5. Lower the engine into the workstand and insert the eight AN7-11A bolts through the flanges and into the mount roll fittings. Tighten these bolts and check that the NAS1356-S2S09F pins of the adapter kit pivot are installed. Remove the pins from the hoist fittings and remove the hoisting sling. Drain engine hydraulic and lubricating oil systems if the engine is to be turned to the horizontal position.
- 2.4.5. Maintenance of Basic Weight and Balance Records. The Basic Weight and Balance Record (Form II-4) is a continuous history of the basic weight and centers of gravity resulting from structural and equipment changes. At all times, the last entry on this form is considered the current basic weight and center of gravity status of the basic gimballed equipment. The form must be completed each time the gimballed equipment is weighed and

is used to record all changes which affect its basic weight and balance. This form should be checked before the vehicle is balanced for a particular flight (see Section III) and loading personnel should refer to this form before preparing any load.

When the gimballed equipment is reweighed, the weights and moments entered in the form must reflect the basic weight as derived on Weighing Record Form II-2, sheet 3, and Weighing Record Form II-3, sheet 4. If an item is to be added to or subtracted from the gimballed equipment listed in the LLRV Equipment Checklist, Table 1-8, enter the item number, description, applicable weight, and moments on the Gimballed Equipment Basic Weight and Balance Record Form II-4. If the item is permanently added or removed, make the necessary changes to the LLRV equipment checklist. Any change or modification which is caused by a specific order should carry a reference to the order number and date which authorizes the change.

- 2.5. BASIC WEIGHT AND CENTER OF GRAVITY DETERMINATION OF THE COMPLETE VEHICLE.
- 2.5.1. General. The object of this procedure is to obtain an accurate weight and center of gravity of the vehicle in the basic weight condition. This will serve as the starting point for obtaining a properly balanced vehicle at an operating weight empty condition.

### CAUTION

It is extremely important that this procedure be accurately performed. A vehicle which is flown with the centers of gravity outside the established limits may result in unmanageable control problems and possible disaster. Every precaution must be taken to ensure that the basic weight and centers of gravity are correct.

### 2.5.2. Preparation for Weighing. -

- Step 1. Determine the weight and lateral centers of gravity of the center of gravity fixture as described in Paragraph 2.2.
- Step 2. Determine the weight and vertical center of gravity of the gimballed equipment as described in Paragraph 2.3.

- Step 3. Determine the lateral centers of gravity of the gimballed equipment as described in Paragraph 2.4.
- Step 4. Obtain three scales of at least 2000 pounds capacity and accurate to within  $\pm 0.50$  pound (either platform or flush type). Ensure that the scales are correctly calibrated and levelled.
- Step 5. Position and level the weighing fixture as described in Paragraph 2.2.2.

  Note scale readings and compare with figures obtained when fixture was last weighed. If a discrepancy exists, determine and rectify the cause before proceeding.
- 2.5.3. Procedure for Positioning the LLRV on the Center of Gravity Fixture. -
  - Step 1. Remove twelve NAS674-4H bolts from the bottom side of the LLRV engine mount. These bolts are located as follows:
    - (a) Four centered about a point 14.387 inches forward of the engine and 14.205 inches to the right side.
    - (b) Four centered about a point 14.387 inches forward of the engine and 14.205 inches to the left side.

### CAUTION

Do not remove the seven 3/16 inch diameter bolts found in the same general area.

- (c) Four centered about a point on the LLRV longitudinal axis and 20.218 inches aft of the lateral engine centerline.
- Step 2. Loosely attach three engine mount plates with centering pins pointing down to the locations described in Step 1 using twelve NAS674-16H bolts. The engine mount plates consist of two part number 503 and one part number 502. Part number 502 has shorter hole spacings and is located at the most aft mounting point (location (c) in Step 1).
- Step 3. Remove the large tang from master ring (at engine mount position) and position the master ring beneath the LLRV engine so that the areas stamped FWD and USE AGAINST VEHICLE are properly oriented with respect to the LLRV.

- Raise the master ring up and around the LLRV engine assembly until the aft tang on the inside diameter of the ring engages the unused aft main engine mount slot. Replace and engage the forward tang in the unused forward right engine mount slot. During this operation, the spherical ends of the centering pins in the loosely attached engine mount plates are inserted into appropriate positioning holes of the master ring.
- Step 5. Attach master ring to LLRV engine using two captive pins, part number 7161-421028-1, inserted through the ring tangs and main engine mounts.
- Step 6. Tighten the twelve NAS674 -16H bolts in the engine mount plates.
- Step 7. Remove the large tang from the master ring and remove the master ring from engine assembly. Replace tang on master ring.
- Step 8. Install the gimbal ground locks. (See Figure 2-5.)
- Step 9. Remove the four AN5-10 bolts which attach the drogue parachute cables to the four top corners of the LLRV center body structure.
- Step 10. Attach the link of the LLRV Hoist Sling, part number 7161-753002, to an overhead hoisting device of two ton minimum capacity.
- Step 11. Using the hoisting device, lower the LLRV hoist sling so that the drop cables can be attached with AN5 bolts to the drogue parachute terminals located at each of the four top corners of the LLRV center body structure.

  These terminals are made available by removal of the bolts in Step 9.
- Step 12. Position the support truss assembly in the area accessible to the overhead hoisting device with the FWD notation on the triangular base oriented properly with respect to forward on the LLRV.
- Step 13. Using the overhead hoisting device, lift and position the complete LLRV to permit clearance between the engine exhaust cone and the top of the support truss assembly. Lower the complete LLRV on to the CG fixture until the centering pins of the engine mount plates slip into the alignment holes of the mount fittings attached to the top ring of the support truss assembly.

To be supplied

Figure 2-5. Gimbal Ground Locks

### CAUTION

Proceed with extreme care when lowering the LLRV to assure that sufficient clearances exist between components and fixture and that no damage occurs as the alignment pins engage the mount fittings.

- Step 14. Secure the LLRV to the CG fixture by installing three 1/2-inch diameter socket head cap screws, with warning streamers, up through the top of the mount fittings and into the engine mount plates.
- Step 15. Slack off, but do not remove the LLRV hoist sling. This is a precautionary measure to prevent possible damage to the LLRV by tipping during the leveling operation. A view of the vehicle mounted on the center of gravity fixture is shown in Figure 2-6.
- 2.5.4. Determination of Basic Weight and Lateral Centers of Gravity of the Vehicle Less Gimballed Equipment. -
  - Check the vehicle and gimballed equipment against the equipment checklist (Table 1-8). Note all discrepancies. Make certain fuel and hydrogen peroxide tanks are drained before weighing.
  - Step 2. Seat and properly strap in the designated pilot in the cockpit, with his feet and hands resting lightly on the appropriate controls. The pilot must wear his normal flight suit and equipment. If the designated pilot is not available for weighing, a substitute pilot who most closely approximates the actual pilot's weight should be used. A pilot must always be aboard during weighing to eliminate any tendency of the vehicle to topple and to avoid the necessity of making large center of gravity corrections for the final balancing. Record the weight of the pilot or his substitute.

To be supplied by NASA

Figure 2-6. Vehicle on Center of Gravity Fixture

- Step 3. Level the vehicle utilizing the leveling lugs provided and a Clinometer,

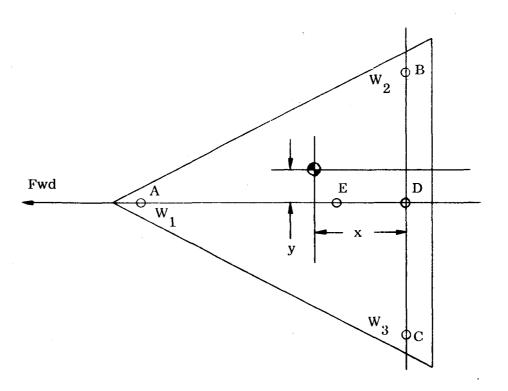
  Hilger and Watts Model 75022 or equivalent, adjusting the pitch and roll

  gimbal locks. The vehicle must be levelled as accurately as possible and
  within ±10 minutes, maximum.
- Step 4. Remove the hoist sling and replace the four AN5 bolts in the drogue parachute attachment fittings.
- Record the scale indications on Weighing Record Form II-5, Sheet 1.

  Repeat the readings as necessary to ensure accurate results. Upset the beam on each scale between subsequent readings. Locate the combined center of gravity of the vehicle and fixture by taking moments:

$$x = \left(\frac{W_1 \times AD}{W_1 + W_2 + W_3}\right) \text{ inches}$$

$$y = \left(\frac{(W_2 \times BD) - (W_3 \times CD)}{W_1 + W_2 + W_3}\right) \text{ inches}$$



Dimensions AD, BD, CD and DE are inscribed on the fixture.

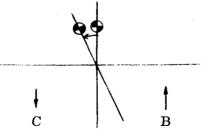
- Step 6. Determine the lateral centers of gravity of the basic vehicle. The weight and center of gravity of the fixture and basic gimballed equipment was obtained in Paragraph 2.4. Adjust these figures as necessary and obtain the basic weight and lateral centers of gravity of the vehicle by subtraction. It is obviously an advantage if the configuration of the gimballed equipment is the same for both weighings. In particular, the fluid systems should reflect the basic configuration. Sheets 1 through 5 of the Weighing Record Form II-5 when completed, will give the actual lateral centers of gravity of the vehicle.
- 2.5.5 Determination of the Vertical Center of Gravity of the Basic Vehicle. If the value of D<sub>1</sub>, as obtained on Sheet 5 of Weighing Record Form II-5, is less than 0.1, the vertical center of gravity may be found as described in Paragraph 2.5.5.1. However, if the value of D<sub>1</sub> is greater than 0.1, proceed as directed in Paragraph 2.5.5.2.

### 2.5.5.1. Value of $D_1$ Less Than 0.1.-

Remove the AN5 bolts from the drogue parachute cable attachment fittings and attach the hoist sling. Remove the gimbal lock on the roll actuator and carefully lower the hoist sling to develop some slack in the sling cables. Since the value of D<sub>1</sub> is less than 0.1, the center of gravity is directly above or below the vehicle roll axis and the vehicle should have no tendency to roll. Using caution, roll the vehicle a few degrees right or left by manually grasping the two fore and aft legs. Note changes in scale readings at jack points B and C and use the following diagrams to determine whether the vertical center of gravity is above or below waterline 200.0.

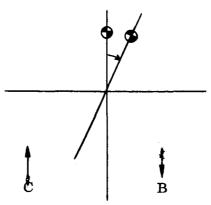
### Case 1. Vertical Center of Gravity Above WL200. -

(a) Roll vehicle to left. - Scale reading at C increases while B decreases. Vehicle tends to continue rolling to left.



View Looking Forward Along Roll Axis

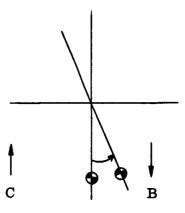
(b) Roll vehicle to right. - Scale reading at B increases while C decreases. Vehicle tends to continue rolling to right.



View Looking Forward Along Roll Axis

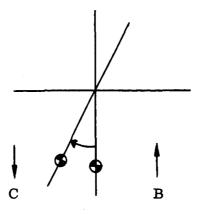
### Case 2. Vertical Center of Gravity Below WL200. -

(a) Roll vehicle to left. - Scale reading at C decreases while B increases. Vehicle tends to return to level position.



View Looking Forward Along Roll Axis

(b) Roll vehicle to right. - Scale reading at B decreases while C increases. Vehicle tends to return to level position.



View Looking Forward Along Roll Axis

Step 2. Having now determined whether the vertical center of gravity is above or below waterline 200, attach the special gimbal lock and lock the vehicle at a roll angle of between 25 and 30 degrees left or right.

### CAUTION

Ensure that the hoist sling is securely attached during this operation. When the vehicle is locked in the rolled position, remove the hoist sling and replace the AN5 bolts.

- Note the scale indication at jackpoint A. If this reading has changed more than plus or minus one pound from the reading taken when the vehicle was level, check the vehicle pitch angle using the clinometer.

  Adjust the pitch gimbal lock as necessary to duplicate the pitch angle reading when the vehicle was level.
- Record the scale indications on Sheet 5 of Weighing Record Form II-5.

  Measure the angle of roll using a clinometer and the level lugs provided.

  Repeat the scale readings as necessary to ensure accuracy, upsetting the scale beams between subsequent readings. The vertical center of gravity can now be located by performing the computations on Weighing Record Form II-5, Sheet 6. Completion of Sheets 7 and 8 will give the vertical center of gravity of the basic vehicle. When the vertical center of gravity has been determined, proceed as directed in Paragraph 2.5.6 and subsequent.

### 2.5.5.2. Value of $\mathbf{D}_1$ Greater Than 0.1. -

Step 1. Remove the AN5 bolts from the drogue parachute attachment fittings and attach the hoist sling. Remove the gimbal lock on the roll actuator and carefully lower the hoist sling to develop some slack in the sling cables. Since the valve of D<sub>1</sub> is greater than 0.1, the center of gravity is to one side of the vehicle roll axis. Thus the vehicle will have a tendency to roll. If the center of gravity is to the right side of the roll axis, the vehicle will roll to the right, and vice versa.

Using extreme caution, allow the vehicle to roll about five degrees without restraint, but with the hoist sling still attached. Ensure that the vehicle starts to roll from the level position and repeat the process until results are consistent.

Step 2. If the unrestrained vehicle rolled to the right, the gimbal lock must now be attached such that the vehicle is rolled to the left and vice versa, the object being to always raise the center of gravity when rolling the vehicle.

Insert the special gimbal lock to roll the vehicle about 25 or 30 degrees.

### **CAUTION**

Ensure that the hoist sling is securely attached during this operation. When the vehicle is locked in the rolled position, remove the hoist sling and replace the AN5 bolts.

- Step 3. Note the scale indication at jackpoint A. If this reading has changed by more than plus or minus one pound from the reading taken when the vehicle was level, check the vehicle pitch angle using the clinometer.

  Adjust the pitch gimbal lock as necessary to duplicate the pitch angle reading when the vehicle was level.
- Step 4. Record the scale indications as shown on Weighing Record Form II-5,
  Sheet 5. Measure the angle of roll using the clinometer and the level
  lugs provided. Repeat the scale readings as necessary to ensure
  accuracy, upsetting the scale beams between subsequent readings. The
  vertical center of gravity can now be located by performing the computations on Weighing Record Form II-5, Sheet 6. Completion of Sheets 7 and
  8 of Form II-5 will give the vertical center of gravity of the basic vehicle.

- 2.5.6. Procedure for Removing the LLRV from the Center of Gravity Fixture. -
  - Step 1. Remove the four AN5 bolts from the drogue parachute cable attachment fittings and attach the hoist sling. Remove the special gimbal lock and carefully return the LLRV to the level position. Insert the level roll gimbal lock and remove the pilot from the cockpit.

### **CAUTION**

Do not attempt to raise the overhead hoisting device at this time as severe damage to the LLRV could result. The hoist sling is attached at this time to eliminate possible tipping and subsequent damage to the LLRV during scale and fixture removal operations.

- Step 2. Unlock the casters and transfer the weight of the fixture and the LLRV from the scales to the casters by turning the adjusting screws. Remove the scales or the 10-1/4-inch spacers if a flush weighing facility is used.
- Step 3. Remove three 1/2-inch diameter socket head cap screws and warning streamers. These screws attach the LLRV engine mount plates to the mount fittings of the CG fixture.

### **CAUTION**

Do not under any circumstances attempt to hoist the LLRV without first removing the three 1/2-inch diameter screws. Serious damage to the engine mount could occur if the LLRV is hoisted while still attached to the fixture.

Step 4. Carefully raise the LLRV out of the CG fixture to a point where the engine exhaust cone will clear the top fittings of the truss, using the overhead hoisting device.

### CAUTION

Proceed with extreme care when raising the LLRV out of the fixture to assure that sufficient clearance exists between the vehicle components and the fixture.

- Step 5. Remove the support truss assembly from beneath the LLRV. Check and record the scale zero errors.
- Step 6. Carefully lower the LLRV to the floor using the overhead hoisting device.
- Step 7. Remove the four AN5 bolts which attach the LLRV hoist sling to the drogue parachute terminals.
- Step 8. Remove the overhead hoisting device and the LLRV hoist sling. Secure the LLRV drogue parachute terminals to the ball end terminals at the corners of the center body structure with AN5-10 bolts.
- Step 9. Remove three engine mount plates from under side of LLRV engine mount. These plates are attached with twelve NAS674-16H bolts. Install twelve NAS674-4H bolts in the holes.
- 2.5.7. Maintenance of Basic Weight and Balance Records. The Basic Weight and Balance Record, Form II-6, is a continuous history of the basic weight and centers of gravity resulting from structural and equipment changes. At all times, the last entry on this form is considered the current basic weight and center of gravity status of the basic vehicle.

Form II-6 must be completed each time the vehicle is weighed and should be used to record all changes which affect the vehicle's basic weight and balance. The following are typical of such changes:

- (a) Any alterations made to the equipment or structure, whether temporary or permanent.
- (b) The addition or subtraction of ballast.
- (c) Movement of the aft equipment platform.
- (d) Reweighing the vehicle.

Form II-6 should be checked before the vehicle is balanced for a particular flight. Loading personnel should refer to this form before preparing any load.

When the vehicle is reweighed, the weight and moments entered in the form must reflect the basic weight as derived on Sheets 5 and 8 of the Weighing Record Form II-5. The configuration of the aft equipment platform must be the same as noted on Sheet 1 of Form II-5.

If an item which is to be added to or removed from the vehicle is listed in the equipment checklist (Table 1-8), enter the item number, description, applicable weight, and moments on the basic weight and balance record. If the item is permanently added or removed, make the necessary changes to the equipment checklist. Any change or modification caused by a specific order should carry a reference to the order number and date which authorizes the change.

### 2.6. AFT EQUIPMENT PLATFORM.

- 2.6.1. General. The aft equipment platform is illustrated in Figure 2-7. Its function is to provide those moment changes necessary to maintain a required vehicle center of gravity location in three axes simultaneously. Provisions are therefore made to allow the movement of weights in three mutually perpendicular directions to produce the required moments. The movable items on the aft equipment platform can be broken down into three major units as indicated in Paragraphs 2.6.1.1 through 2.6.1.3.
- 2.6.1.1. <u>Items Movable Vertically Up and Down.</u> All items of equipment and structure aft of the vertical beams at Station 270 can be moved a total of ±5.5 inches up or down from the neutral position in increments of one inch.
- 2.6.1.2. Items Movable Horizontally Forward and Aft. There are two groups of equipment which fall under this heading.
  - (a) All equipment on the adjustable platform which can be moved forward and aft for a total distance of  $\pm 16.25$  inches in increments of 1.25 inches.
  - (b) The doppler receiver-transmitter assembly mounted underneath the platform which can be moved a total distance of  $\pm 9.375$  inches from the neutral position in increments of 1.25 inches.

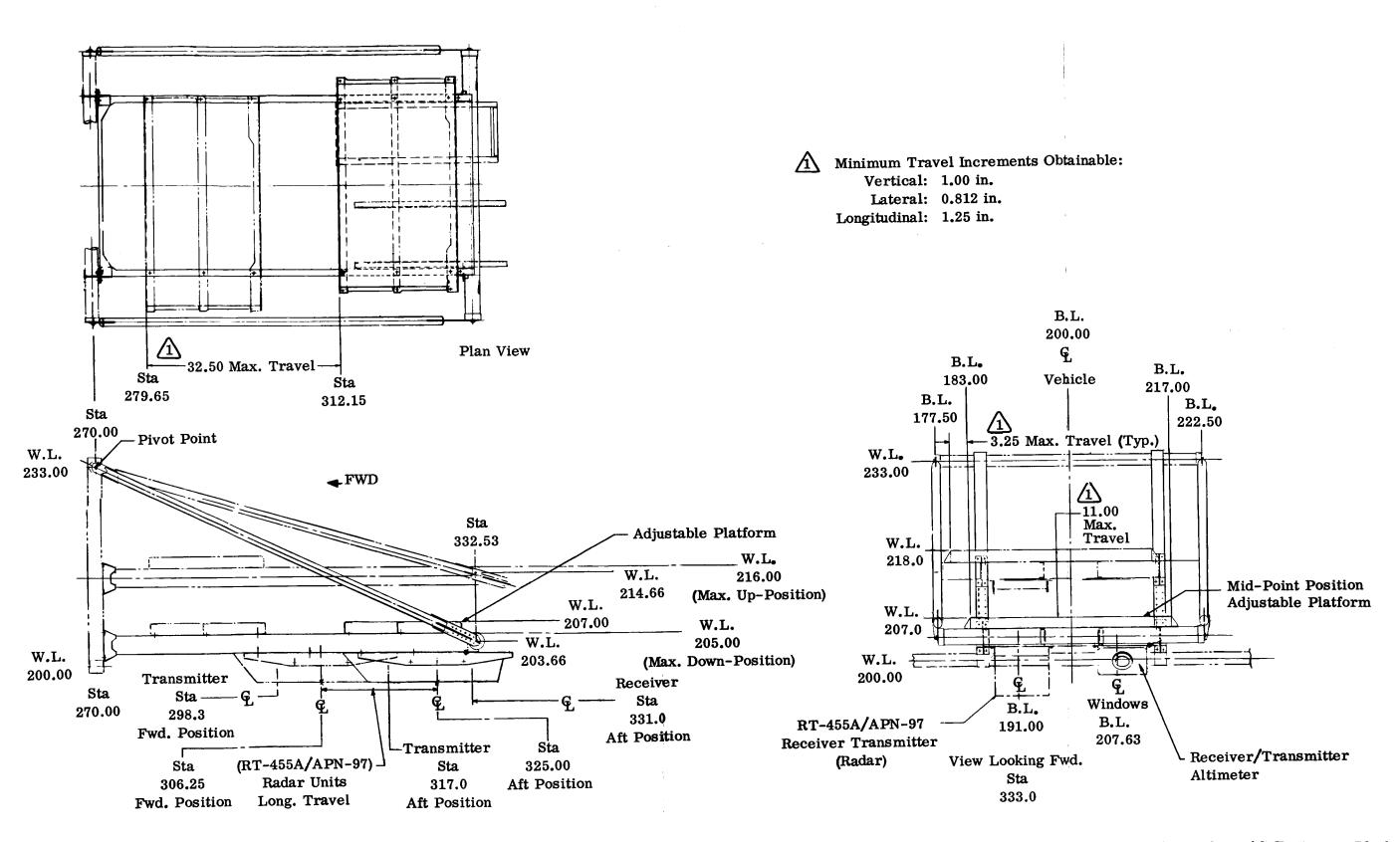


Figure 2-7. Aft Equipment Platform

- 2.6.1.3. <u>Items Movable Laterally.</u> Lateral movement is confined to those items mounted on the adjustable platform. A total movement of ±3.25 inches is possible, in increments of 0.812 inch.
- 2.6.2. Determination of Change in Moment as Equipment is Moved. In order to be able to adjust the vehicle center of gravity with the minimum of inconvenience, it is necessary to know the exact moment change accompanying the movement of the three major units of equipment. An approximate figure can be obtained by weighing the various movable units previously described. Knowing the vehicle weight and center of gravity and the increments through which the movable weight can be moved, it is a straight forward matter to calculate the total movement required to effect the required adjustment.

However, due to the indeterminate effects of cable assemblies, the actual moment change will be somewhat different. Measurement of the actual change should be carried out with the vehicle mounted on the center of gravity fixture as described in Paragraph 2.5. The movable units should be adjusted in steps and careful calculations made of the center of gravity changes produced. Thus a table can be constructed to show the precise actual c.g. with the movable units at various locations.

2.6.3. Maintenance of Basic Weight Records. - The Basic Weight Record, Form II-7, is a continuous history of the basic weight of the movable units resulting from structural and equipment changes. At all times, the last entry on these forms is considered the current basic weight status. Form II-7 must be completed each time the movable equipment is weighed and all changes which affect the weight must be recorded. This form should be checked before the vehicle is balanced for any particular flight or operation.

If an item which is to be added to or subtracted from the movable equipment is listed in the equipment checklist (Table 1-8), enter the item number, description, and applicable weight on the basic weight record. If the item is permanently added or removed, make the necessary changes to the equipment checklist.

Any change or modification caused by a specific order should carry a reference to the order number and date which authorizes the change.

All structural and equipment changes which affect the weight of movable units must also be shown on the vehicle basic weight and balance record. Those changes which do not

affect the weight but which do affect the location of the movable units will appear only on the vehicle record. Refer to Paragraph 2.5.7.

- 2.7. POWER PLANT CENTER OF GRAVITY AND THRUSTLINE OFFSETS.
- 2.7.1. General. Due to the effect of the engine gearbox, generator, fuel control unit, and other unsymmetrically located items, the power plant center of gravity will not coincide with the engine thrustline. This produces moments in flight which must be compensated.
- 2.7.2. Method of Compensation. The moments created by the engine center of gravity and thrustline offset are compensated by adjusting the vehicle center of gravity to produce an equal and opposite moment about the intersection of the pitch and roll axes.

This is accomplished in practice by adjusting the aft equipment platform to produce a vehicle center of gravity at operating weight empty, which coincides with the intersection of the vehicle pitch and roll axes. The procedure for achieving this result is fully explained in Paragraph 3.2.

### 1. VEHICLE, GIMBALLED EQUIPMENT, AND FIXTURE

DATE	PLACE				WEIGHE	D BY	
ENGINE NO.	VEHICI	E NO.		PILO	TS WEIG		POUNDS
VEHICLE ATTIT	UDE (LEVEL)	PITCH	0	ROLI	_	D	
FUEL SYSTEM:	DRY I	INES ONLY	FULL [	]	LB	TANKS	EMPTY [
ROCKET SYSTEM	M: DRY 🔲 I	INES ONLY	FULL [		LB	TANKS	ЕМРТҮ 🔲
SCALES USED							,
LOCATION OF M	IOVABLE EQUI	PMENT:					
(b) Items with (c) Doppler Re	Vertical Travel Lateral Travel: c/Trans - Hori Platform - Hor	zontal:					
JACKPOINT	SCALE READING	TARE	1	ET GHT			W <sub>2</sub> B
A			W <sub>1</sub>		Fwd		1
В			W <sub>2</sub>		-   <del>- " - </del>	$\Theta_{\mathbf{W_1}}^{\mathbf{A}}$	e D
С			$W_3$				yrw
Total as Weighed							W <sub>3</sub> oC

### MEASUREMENTS (Inscribed on Fixture)

AD = \_\_\_\_\_ inches, the distance from jackpoint A to BC
BD = \_\_\_\_\_ inches, the distance from jackpoint B to AD
DC = \_\_\_\_\_ inches, the distance from jackpoint C to AD
DE = \_\_\_\_\_ inches, the distance from BC to the projected engine vertical centerline

### CENTER OF GRAVITY CALCULATIONS

x = distance of center of gravity from BC y = distance of center of gravity from AD

$$x = \left(\frac{W_1 \times AD}{W_1 + W_2 + W_3}\right)$$
 inches = \_\_\_\_\_ inches

$$y = \left( \frac{(W_2 \times BD) - (W_3 \times CD)}{W_1 + W_2 + W_3} \right)$$
 inches

Locate the center of gravity with respect to AD by comparing  $\boldsymbol{W}_2$  and  $\boldsymbol{W}_3$ .

### 1. VEHICLE, GIMBALLED EQUIPMENT, AND FIXTURE

Convert centers of gravity x and y to vehicle Body Stations (X), and Buttock Lines (Y).

BS 
$$X = (200 + ED - x)$$
 inches = \_\_\_\_\_ inches

BL 
$$Y = (200 \pm y)$$
 inches = \_\_\_\_\_ inches

Determine the correct sign for y by comparing the values of  $\boldsymbol{W}_2$  and  $\boldsymbol{W}_3$ .

If 
$$W_3 > W_2$$
, y is negative

If 
$$W_2 > W_3$$
, y is positive

If 
$$W_2 = W_3$$
, y is zero

# 2. WEIGHT AND CENTER OF GRAVITY OF GIMBALLED EQUIPMENT AND FIXTURE

·		COLUMN	I		
BASIC ITEMS NOT ON GIMBALLED EQUIPMENT WHEN WEIGHED	WEIGHT W POUNDS	ARM x INCHES	MOMENT Wx POUND.	ARM y INCHES	MOMENT Wy POUND - INCHES
Total Column I Items					

# 2. WEIGHT AND CENTER OF GRAVITY OF GIMBALLED EQUIPMENT AND FIXTURE (CONT)

		COLUMN	II	,	
ITEMS WEIGHED BUT NOT PART OF BASIC GIMBALLED EQUIPMENT	WEIGHT POUNDS W	ARM x INCHES	MOMENT Wx POUND- INCHES	ARM y INCHES	MOMENT Wy POUND- INCHES
	n				
Total Column II Items				and the second s	
DESCRIPTION	WEIGHT W POUNDS	ARM x INCHES	MOMENT Wx POUND- INCHES	ARM y INCHES	MOMENT Wy POUND- INCHES
Fixture and Basic Gimballed Equipment (Form II-3, Sheet 3)					
Less Total Column I Items	-				-
Plus Total Column II Items	+		+		+
Fixture and Gimballed Equipment as Weighed					

# 3. BASIC WEIGHT AND LATERAL CENTERS OF GRAVITY OF VEHICLE

COLUMN I											
ITEMS WEIGHED BUT NOT PART OF BASIC VEHICLE	WEIGHT W POUNDS	ARM x INCHES	MOMENT Wx POUND- INCHES	ARM y INCHES	MOMENT Wy POUND- INCHES						
Pitch Gimbal Lock											
Roll Gimbal Lock											
Pilot											
				<u> </u>							
-											
Total Column I Items											

	COLUMN II												
BASIC ITEMS NOT ON VEHICLE WHEN WEIGHED	WEIGHT W POUNDS	ARM x INCHES	MOMENT Wx POUND- INCHES	ARM y INCHES	MOMENT Wy POUND- INCHES								
JP4 In Lines													
H <sub>2</sub> O <sub>2</sub> In Lines													
Total Column II Items													

# 3. BASIC WEIGHT AND LATERAL CENTERS OF GRAVITY OF VEHICLE (CONT)

DESCRIPTION	WEIGHT W POUNDS	ARM x INCHES	MOMENT Wx POUND- INCHES	ARM y INCHES	MOMENT Wy POUND- INCHES
Total as Weighed (Sheets 1 and 2)					
Fixture and Gimballed Equipment as Weighed (Sheet 3)	<b>-</b>		-		_
Less Total Column I Items (Sheet 4)	-		-		-
Plus Total Column II Items (Sheet 4)	+		+		+
Total Vehicle Only Basic Weight					

D,	$= (-200 \pm y) =$	$(-200 \pm$	) = +	inches
----	--------------------	-------------	-------	--------

Note: The absolute value of  $\mathrm{D}_1$  is required.  $\mathrm{D}_1$  must always be positive, regardless of the value of y.

### 4. VERTICAL CENTER OF GRAVITY OF VEHICLE

ROLL ANGLE:	RIGHT LEFT	cot θ	cosec θ	
JACKPOINT	SCALE READING	TARE	NET WEIGHT	
A			W <sub>1</sub>	WoB
В			W <sub>2</sub>	
С			W <sub>3</sub>	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$
Total as Weighed				w <sub>3</sub> oc

MEASUREMENTS (Inscribed on Fixture)

BD	=	 inches,	the	${\tt distance}$	${\bf from}$	jackpoint	${f B}$	to	AD
CD	=	 inches,	the	distance	from	jackpoint	$\mathbf{C}$	to	AD

### 4. VERTICAL CENTER OF GRAVITY OF VEHICLE (CONT)

### VERTICAL CENTER OF GRAVITY CALCULATIONS

 $D_9$  = distance of center of gravity from AD at roll angle of  $\theta$  degrees:

$$D_2 = \left[ \frac{(W_{2 \times BD}) - (W_{3 \times CD})}{W_1 + W_2 + W_3} \right]$$
 inches = \_\_\_\_\_ inches.

a. Value of  $D_1 < 0.1$ .

If the value of  $\mathbf{D}_1$  was less than 0.1 and the vertical center of gravity was above WL200. --

Vertical CG = 
$$WL200 + D_2 \csc \theta$$
  
=  $WL200 +$   
=  $WL$ 

If the value of  $\mathbf{D}_1$  was less than 0.1 and the vertical center of gravity was below WL200. -

Vertical CG = 
$$WL200 - D_2 \csc \theta$$
  
=  $WL200 -$   
=  $WL$ 

b. Value of  $D_1 > 0.1$ .

Vertical center of gravity

= 
$$WL200 + (D_1 \cot \theta - D_2 \csc \theta)$$
  
=  $WL200 + ($  )

Form II-5

WEIGHING RECORD

# 4. VERTICAL CENTER OF GRAVITY OF VEHICLE (CONT)

	COLUMN I	I NI			COLUMN II	II N	
ITEMS WEIGHED BUT NOT PART OF BASIC VEHICLE	WEIGHT W POUNDS	ARM z INCHES	MOMENT WZ POUND-INCHES	BASIC ITEMS NOT ON VEHICLE WHEN WEIGHED	WEIGHT W POUNDS	ARM z INCHES	ARM MOMENT  Z WZ INCHES POUND-INCHES
Pitch Gimbal Lock				JP4 in Lines			
Special Roll Gimbal Lock	i			H <sub>2</sub> O <sub>2</sub> in Lines			
Pilot							
Total Column I Items				Total Column II Items			

DESCRIPTION	WEIGHT	ARM z INCHES
Total as Weighed (Sheet 5)		
Fixture and Gimballed Equipment as Weighed (Sheet 3)	1	
Vehicle Only as Weighed		From Sheet 6

### 4. VERTICAL CENTER OF GRAVITY OF VEHICLE (CONT)

DESCRIPTION	WEIGHT W POUNDS	ARM z INCHES	MOMENT Wz POUND-INCHES
Vehicle Only as Weighed (Sheet 7)			
Less Total Column I Items (Sheet 7)	-		-
Plus Total Column II Items (Sheet 7)	+		+
Total Vehicle Only Basic Weight			

The vehicle Basic Weight obtained here must agree with the basic weight obtained on Sheet 5.

Form II-6

BASIC WEIGHT AND BALANCE RECORD

CONTINUOUS HISTORY OF CHANGES IN STRUCTURE OR EQUIPMENT AFFECTING WEIGHT AND BALANCE

MOMENT WEIGHT AND MOMENT CHANGES, RUNNING TOTAL, BASIC VEHICLE POUND-INCHES INCHES ARMMOMENT y POUND-INCHES Wy POUND-ARMPOUNDS INCHES INCHES MOMENT POUND-ARMWEIGHT COMPLETE DESCRIPTION OF CHANGE Vehicle No. DATE

Form II-7

BASIC WEIGHT RECORD - MOVABLE EQUIPMENT

CONTINUOUS HISTORY OF CHANGES IN STRUCTURE OR EQUIPMENT AFFECTING WEIGHT

SHEET UNIT UNIT DESCRIPTION: VEHICLE NO.

	RUNNING TOTAL UNIT	WEIGHT FOOTING						
L CHANGE	DDED(+) REMOVED (-) 1/2 WEIGHT	FOUNDS						
METAW	ADDED(+) WEIGHT	POUNDS						
	DESCRIPTION OF	ARTICLE OR MODIFICATION						
	ITEM NO.	OUT						
	II	NI.			-		 -	
		DATE			:			

### SECTION III

### FLIGHT LOADING AND BALANCING DATA

### 3.1. BALANCING AND LOADING PROCEDURES.

Balancing and loading of this vehicle are part of one and the same operation. Each particular flight must be balanced to account for variations in research equipment weights and/or individual pilot weights. Since these changes affect both operating weight empty and gross takeoff weight, vehicle balancing and loading become inseparable.

The following changes to operating weight empty are typical of those which will require that the vehicle be rebalanced:

- (a) Substitution of pilots.
- (b) Addition or removal of equipment.
- (c) Change in helium gas pressure.
- (d) Addition or removal of jet engine intake screens.

A satisfactory balance will be maintained indefinitely, provided the vehicle configuration and operating weight empty remain constant.

### 3.2. BALANCING AND LOADING FOR FLIGHT.

- 3.2.1. Preliminary Requirements. The vehicle and gimballed equipment must be accurately weighed as described in Section II of this handbook. All basic weight record forms must be complete and up-to-date. A careful check should be made to ensure that no changes have been made to the vehicle or its equipment since the last entry in the Basic Weight and Balance Record Form II-6.
- 3.2.2. Weight and Balance Clearance Form. The Weight and Balance Clearance Form III-1, records the weight and balance status of the vehicle for each flight. It serves as a worksheet on which the weight and balance computer records his calculations and all pertinent data relating to the loading.

An original and carbon copy of this form must be prepared for each loading. The original, carrying the signatures of responsibility, must be retained with the flight records to serve as the certificate of proper weight and balance clearance. The carbon copy should be filed for future reference.

Compare with Actual Values   X   199.75 to 200.25   Z   199.50 to 200.00   T   199.50 to 200.00   T   199.50 to 200.00   T   200.00	Form III-1			•								FLIGH'	T DATE	
No.   ITEM AND SOURCE   WEIGHT ARM   NO.   NOMENT   NOW   ARM   W   ARM	1			W	EIGHT AND BALANCE C	LEARANCE - LI	ıRV	FLIGHT NO.						
2 LIMITATIONS  NO. STEM AND SOURCE WILEST ARM NOMES OF CONTROL AND SOURCE WILEST ARM NOMES OF CONTROL AND SOURCE WILEST ARM NOMES OF CONTROL AND SOURCE WILEST ARM NOMES OF CONTROL AND SOURCE WILEST ARM NOMES OF CONTROL AND SOURCE WILEST ARM NOMES OF CONTROL AND SOURCE WILEST ARM NOMES OF CONTROL AND SOURCE WILEST AND	FACILITY	VEHICLE NO.	ENGI	NE NO	). PILO	Т	PILOT WEIGHT	Г	LB R	UNWAY AL	TITUDE	_FTAMBIE	NT TEMP	°F
Ask Allowable Gross T.O.W.   B								W	X.	W <sub>X</sub> POUND-	Y	W <sub>y</sub> POUND-	Z	W <sub>z</sub> POUND-
Age			•	3	Basic Vehicle (Basic Wt a	and Balance Reco	rd,) (Form II-6)							
Compare with Actual Values  Y 199.75 to 200.25   Z 189.55 to 200.25   Z 189.55 to 200.25   Z 189.55 to 200.26   S 2 189.55 to 200.26	Max. Allowable Gross T.O.W.	<u>lb</u>		4	Pilot (Table 1-3)									
Table   Adjust Aft Equipment Vertically   (Paragraph 2.6.) Calculations:	Center of Gravity Limits	X 199.75 to 200.25	)	5	Corrections									
Interest   Interest	(Compare with Actual Values)	Y 199.75 to 200.25	<del>}-</del>										<u> </u>	·
S. Vehicle d.ess Gimballed Eqph at O.W.EBalanced Vertically		Z 199.50 to 200.00		7	Adjust Aft Equipment Ver	tically. (Paragra	ph 2.6.) Calculations:							
S. Vehicle Less Gimballed Eqph at O.W.EBalanced Vertically														
9   Cimballed Eqpt (Basic Wt and Balance Record (Form III-4)   10   Corrections:	1.0			0	Wahiala (Laga Cimballad	Fant) at OWF	Rolanged Vertically							
10   Corrections   1   10   Corrections   1   11   Basic Vehicle at O.W.E Unbalanced   1   12   Adjust Aft Equipment, Lat and Hort. (Paragraph 2.6.)   Calculations	(Compare with Estima- ted Landing Fuels Below) H <sub>2</sub> O <sub>2</sub>	lb	-								<del>                                     </del>			
11   Basic Vehicle at O.W.E Unbalanced   12   Adjust AR Equipment, Lat and Horiz. (Paragraph 2.6.)   12   Adjust AR Equipment, Lat and Horiz. (Paragraph 2.6.)   13   Vehicle at O.W.E Balanced   14   Total JP4 system Conditions   14   Total JP4 Fuel Loaded   1b   Total JP4 System:				1										
12   Adjust Aft. Equipment, Lat and Horiz. (Paragraph 2.6.)   12   Adjust Aft. Equipment, Lat and Horiz. (Paragraph 2.6.)   13   Vehicle at O.W.E Balanced   13   Vehicle at O.W.E Balanced   14   Total JP4 Fuel Loaded   1b   Total JP4 fur Tanks   1b   (Table 1-5)   16   Total JP4 in Tanks   1b   (Table 1-4)   17   Total HgO2 Loaded   1b   (Table 1-4)   18   HgO2 System:   Lines Dry   Enter _ lb (Table 1-7)   Enter Zero   18   HgO2 System:   Lines Dry   Enter _ lb (Table 1-7)   19   Total HgO2 Loaded   1b   (Table 1-6)   200.0   2	Estimated Lan	nding Fuels							<del> </del>					
Est. Usage   1b   Est Usage   1b   Est Usage   1b							agraph 2 6 )				+			
Est. Usage   1b   Est Usage   1b	JP4 in Tanks (16) lb H	2O <sub>2</sub> in Tanks (19) lb		12		t and Horiz. (I ar	agraph 2.0.,							
JP4 at Landing Est b H <sub>2</sub> O <sub>2</sub> at Landing Est b H <sub>2</sub> O <sub>2</sub> at Landing Est b H <sub>2</sub> O <sub>2</sub> and JP4 System Conditions  H <sub>2</sub> O <sub>2</sub> and JP4 System Conditions  15 JP4 System:  Lines Dry	Est. Usage - lb E	st Usage - lb												
H <sub>2</sub> O <sub>2</sub> and JP4 System Conditions  H <sub>2</sub> O <sub>2</sub> and JP4 System Conditions  14 Total JP4 Fuel Loaded   lb   15 JP4 System:  Lines Dry   Enter _ lb (Table 1-5) Lines Wet   Enter Zero  18 H <sub>2</sub> O <sub>2</sub> System:  Lines Dry   Enter _ lb (Table 1-7) Lines Wet   Enter Zero  18 H <sub>2</sub> O <sub>2</sub> System:  Lines Wet   Enter Zero  20 Gross Take Off Weight - Balanced  21 Max. Allowable  Remarks and Special Instructions:  24 This Weight and Balance Clearance Applies Only to the Specific Flight and Date for Which it is Issued.												-		
H <sub>2</sub> O <sub>2</sub> and JP4 System Conditions  15 JP4 System:  Lines Dry	JP4 at Landing Est 10 n	202 at Landing Est 10		13	Vehicle at O.W.E Balar	nced								
15 JP4 System:  Lines Dry														
15 JP4 System:  Lines Dry	H O and JP4 Sys	stem Conditions				1 1		ļ	<del>                                     </del>	<del>                                     </del>		<del>                                     </del>	+	+
15 JP4 System:  Lines Dry	2 2						(Table 1-5)							
Lines Dry	15 JP4 System:			1					200.0		200.0			
18 H <sub>2</sub> O <sub>2</sub> System:  Lines Dry														<del></del>
18 H <sub>2</sub> O <sub>2</sub> System:  Lines Dry	Lines Wet Enter 2	Zero		1		<u></u>	(Toblo 1 7)							
Lines Dry Enter lb (Table 1-7) Lines Wet Enter Zero  20 Gross Take Off Weight - Balanced 21 Max. Allowable Gross Take Off Weight 22 Difference: - Over Under Max. Allowable  This Weight and Balance Clearance Applies Only to the Specific Flight and Date for Which it is Issued.	18 H <sub>2</sub> O <sub>2</sub> System:	•	<b> </b>			<del></del>			200.0		200.0			
Lines Wet	Lines Dry Enter	lb (Table 1-7)												
Remarks and Special Instructions:  22 Difference: - Over								<del> </del>	<del> </del>	<b>-</b>	_			
Remarks and Special Instructions:  This Weight and Balance Clearance Applies Only to the Specific Flight and Date for Which it is Issued.	·			1 )			Allowable							
This Weight and Balance Clearance Applies Only to the Specific Flight and Date for Which it is Issued.	Remarks and Special Instruction	ns:		22	Difference Over	older Li max.	71110 W d. 510	<b>-</b>						
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This Weight and Balance Clearance Applies Only to the Specific Flight and Date for Which it is issued.			24					THE LANGE	15	**** 1 ** *	<b>T</b> 3			
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					COMPUTED BY:		WT AND BALANCI	E AUTHO	RITY:	PILOT:				
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Lines between two spaces on the form indicate that a comparison is to be made.

Arrows indicate that a value is to be transferred.

- 3.2.3. Use of Weight and Balance Clearance Form. The following instructions are numbered to identify the various computations with the appropriate spaces on Form III-1.
  - Step 1. Insert the necessary identifying information at the top of the form.
  - Step 2. In the blank spaces of the LIMITATIONS table, enter the maximum allowable gross takeoff weight and minimum landing fuel restrictions obtained from the flight plan.
  - Step 3. Enter the vehicle basic weight, arms, and moments. Obtain these figures from the latest entry on the Basic Weight and Balance Record Form II-6.
  - Step 4. Add the pilot weight and moments using Table 1-3 and the pilot weight entered in Step 1.
  - Step 5. If the vehicle differs from the basic configuration used in Step 3, adjust here for any corrections which are required to bring the vehicle weight to actual flight status. Corrections should be limited to adjustments for last minute additions or removals of equipment. Changes incorporated at this point should be temporary. All permanent changes must be reflected in the basic weight and balance record form. Refer to Paragraph 2.5.7.
  - Step 6. Add together lines from Steps 3, 4, and 5 and obtain the weight and vertical center of gravity of the vehicle (less gimballed items) at operating weight empty.
  - Step 7. Compare the vertical center of gravity obtained in Step 6 with the limitations in Step 2. If the center of gravity falls within the limits, proceed to Step 8.

    If the center of gravity is outside the limits, the aft equipment platform must be adjusted either up or down to correct. First determine which unit of the movable equipment is to be adjusted and obtain its latest weight from the Basic Weight Record Movable Equipment, Form II-7. Determine the moment required to correct the vehicle center of gravity and divide by the movable unit weight. This will give the required movement in inches.

Let  $W_1$  = weight of vehicle.

 $W_{2}$  = weight of movable unit.

 $\triangle_{\mathbf{Z}}$  = distance which vehicle center of gravity must move to fall within limits.

 $\Delta_{\mathbf{u}}^{}$  = distance which movable equipment unit must be moved to provide  $\Delta_{\mathbf{Z}}^{}$ .

Then 
$$\Delta_{\mathbf{u}} = \frac{\mathbf{W_1} \times \Delta_{\mathbf{Z}}}{\mathbf{W_2}}$$

Adjust the movable unit as closely as possible to the figure obtained and enter the actual moment change in the space provided.

### NOTE

Any change in location of the movable equipment must be entered in the Basic Weight and Balance Record Form II-6. It is extremely important that this record is kept current.

- Step 8. Enter the weight from the line of Step 6 and the sum of the moments from the lines of Steps 6 and 7. Compute the new centers of gravity. Compare the value obtained for the vertical center of gravity with the limitations in Step 2. The vertical center of gravity should now fall within the limits.
- Step 9. Enter the gimballed equipment basic weight and lateral and horizontal arms and moments. Obtain these figures from the latest entry on the Gimballed Equipment Basic Weight and Balance Record Form II-4.
- Step 10. If the gimballed equipment differs from the basic configuration used in Step 9, adjust here for any corrections which are required to bring the gimballed equipment weight to actual flight status. Corrections should be limited to adjustments for last minute additions or removals of equipment.

### NOTE

Changes incorporated here should be temporary. All permanent changes must be reflected in the Gimballed Equipment Basic Weight and Balance Record (Paragraph 2.4.5).

- Step 11. Add lines from Steps 8 through 10 and obtain the vehicle operating weight empty and lateral and horizontal centers of gravity.
- Step 12. Compare the centers of gravity obtained in Step 11 with the limitations in Step 2. If they are both within the limits, proceed to Step 13.

If the centers of gravity fall outside the limits, movable units on the aft equipment platform must be adjusted. Follow the procedure laid down in Step 7 and enter the actual moment changes in the spaces provided.

### NOTE

Any change in location of the movable equipment must be entered in the Basic Weight and Balance Record Form II-6. It is extremely important that this record is kept current.

- Step 13. Enter the weight from the line of Step 11 and sum the moments from Steps 11 and 12. Compute the lateral and horizontal centers of gravity of the vehicle at operating weight empty.
  - Compare these centers of gravity with the limitations in Step 2. They should now fall within the limits.
- Step 14. Enter the total weight of JP4 fuel loaded into the vehicle. Ensure that the fuel weight difference between the two tanks does not exceed one pound at takeoff.
- Step 15. Complete this block and enter the appropriate figure in the space provided.

  (Since the JP4 fuel contained in the lines between the tank outlets and engine fuel pump is part of the vehicle basic weight (refer to Paragraph 1.1), it must be subtracted here if the system was dry before loading commenced.)
- Step 16. Subtract line of Step 15 from line of Step 14 and obtain the weight of JP4 fuel actually in the tanks. Using Table 1-4, enter the moments in the spaces provided.
- Step 17. Enter here the total weight of hydrogen peroxide fuel loaded into the vehicle. Ensure that the fuel weight difference between the two tanks does not exceed one pound at takeoff.

- Step 18. Complete this block and enter the appropriate figure in the space provided.

  (Since the hydrogen peroxide contained in the lines between the tank outlets and thruster solenoid valves is part of the vehicle basic weight (refer to Paragraph 1.1 ), it must be subtracted here if the system was dry before loading commenced.)
- Step 19. Subtract line of Step 18 from line of Step 17 and obtain the weight of hydrogen peroxide actually in the tanks. Using Table 1-6, enter the moments in the spaces provided.
- Step 20. Add lines of Steps 13, 16, and 19 and obtain the vehicle gross takeoff weight and centers of gravity. The vertical center of gravity is obtained from line of Step 8.

Compare these centers of gravity with the limitations in Step 2 and ensure that they are still within the limits.

- Step 21. Enter the maximum allowable gross takeoff weight from Step 2.
- Step 22. Find the difference between Steps 20 and 21. Check the appropriate box and enter the weight difference in the space provided. If the vehicle is overweight; then either:
  - (a) Offload JP4 fuel and/or hydrogen peroxide as necessary.
  - (b) Run the engine until it has consumed sufficient fuel to reduce the weight to the point where the vehicle will lift off.
- Step 23. It is important for reasons of flight safety that a check is made on the fuels remaining at landing. From Step 16 (JP4) or Step 19 (H<sub>2</sub>O<sub>2</sub>) enter the total fuel contained in the tanks. Subtract the amount of fuel which will be consumed during the flight. This figure should be obtained from the flight plan.

Compare the estimated landing fuel thus obtained with the minimum landing fuel limitation from Step 2. Load extra fuel as necessary to ensure that minimum landing requirements are met.

This block can also be used to determine how much fuel should be loaded onto the vehicle for any particular flight. The method is as follows:

- (a) Enter the minimum landing fuel requirement in Step 23.
- (b) Add to this the estimated fuel usage figure.
- (c) Enter this total in Step 16 (JP4) or Step 19 ( $H_2O_2$ ).
- (d) Add to this, the value of Step 15 (JP4) or Step 18 ( $\mathrm{H_2O_2}$ ).
- (e) Enter this total at Step 14 (JP4) or Step 17 (H<sub>2</sub>O<sub>2</sub>). This figure will be the total amount of fuel which must be loaded to complete the mission and meet the minimum landing fuel limitations.
- Step 24. When computations are completed, the form should be signed and dated in the spaces provided. Use the remarks and special instructions block to call attention to any unusual features of the loading or balance of the vehicle.